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A Computer Program for Clustering Data Points on the Sphere

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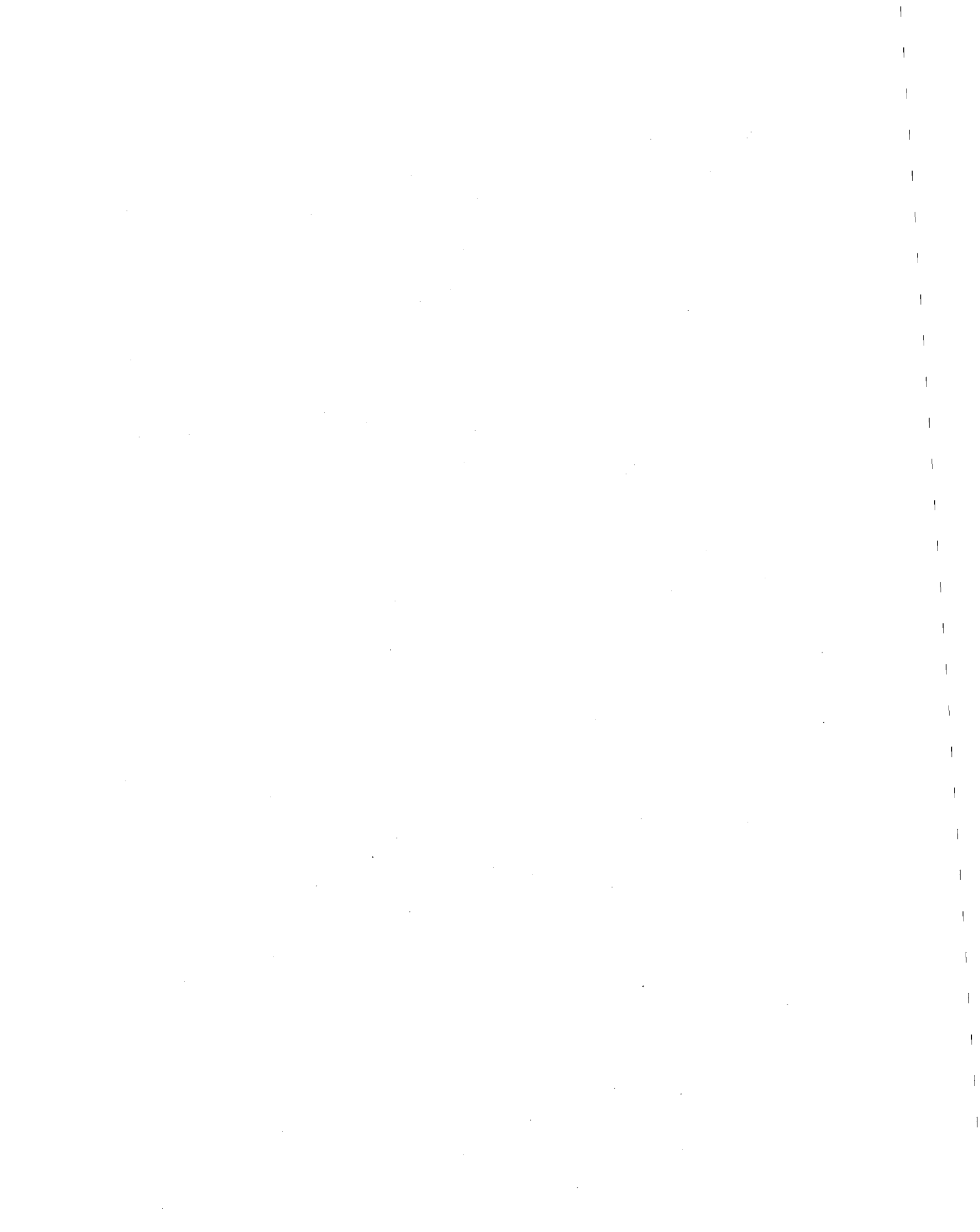
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CONTENTS

	<u>Page</u>
Abstract.....	1
Introduction.....	1
Summary of algorithm.....	1
One-level mode analysis.....	1
The hybrid mode analysis.....	2
Application to the sphere.....	2
The objective function.....	3
Application to fracture orientations.....	3
Program description.....	4
Summary of subroutines of HYBMODE.....	4
Description of output produced by HYBMODE.....	7
Input instructions.....	7
Glossary of frequently used variables.....	8
Program listing.....	9
Example output.....	24
References.....	58

ILLUSTRATIONS

1. Spherical counting cell.....	2
2. Representation of fracture orientations by points on the unit sphere.....	4
3. Flow chart of main program.....	5



A COMPUTER PROGRAM FOR CLUSTERING DATA POINTS ON THE SPHERE

by

Robert J. Shanley¹ and M. Ashraf Mahtab²

ABSTRACT

The computer program, HYBMODE, has been developed to meet the need for a fast and economical method for clustering data points on the sphere. The algorithm used in this development is an extension of D. Wishart's one-level mode analysis. The program can be used to cluster either vectorial or axial data; it is currently being used by the Bureau of Mines to cluster fracture orientations.

INTRODUCTION

An understanding of many phenomena necessitates the collection and analysis of orientation data by physical and earth scientists. Some examples of the types of data collected are magnetic orientations, axes of glacial till pebbles, crystallographic axes, and fracture orientations. Since such measurements can be conveniently represented by unit vectors, it is natural that the methods of cluster analysis be applied to collections of points on the unit sphere. When the data are vectorial the entire sphere may be involved. However, when the data are axial, only one hemisphere is involved. The algorithm used in this report constitutes an improvement over the author's previous work (1)³ which was concerned only with axial data, did not cluster the entire sample, and used a unit cell four times as large as the one currently employed.

SUMMARY OF ALGORITHM

One-Level Mode Analysis

The algorithm used in program HYBMODE is an adaptation of Wishart's one-level mode analysis (2). The purpose of one-level mode analysis is to divide a set of points in any coordinate space into a collection of distinct subsets representing meaningful classifications of the data.

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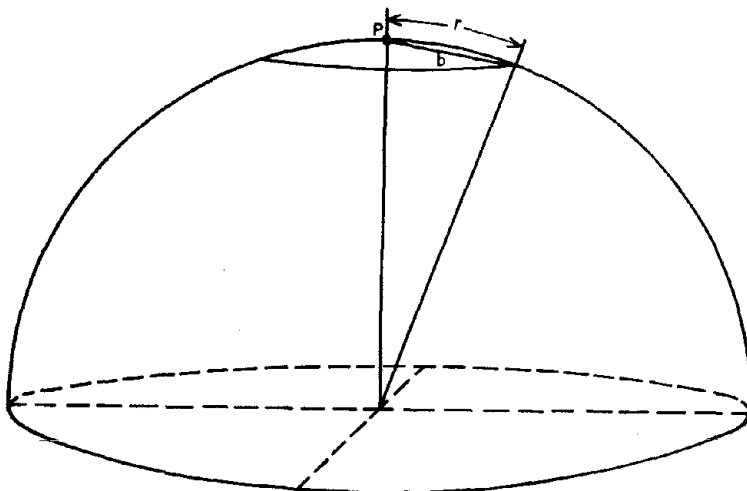
³Underlined numbers in parentheses refer to items in the list of references at the end of this report.

To start a one-level mode analysis, two numbers must be chosen: r , a positive real number which is a distance and k , a positive integer. Spheres of radius r are constructed about every data point. The centers of those spheres containing k or more observations are called dense points. The dense points are then clustered by assigning two dense points separated by a distance less than or equal to r to the same cluster. At this stage, the algorithm has defined distinct sets of points, each point being dense. Next, the nondense points are allocated to clusters using some criterion; in this report, a nondense point is allocated to the cluster containing the closest dense point. Now, every point belongs to a cluster and the clusters are distinct. This marks the end of a one-level mode analysis.

The Hybrid Mode Analysis

A major drawback of one-level mode analysis is that the user must choose both r and k . To make the procedure less arbitrary an additional step is introduced. A value is chosen for r but a test for randomness is used to determine the value of k , namely, a point is defined to be dense if there is a 95 percent probability that the observations within a sphere of radius r about that point do not constitute a random grouping. The randomness test is based on the Poisson distribution (1, p.7).

The addition of the above step to one-level mode analysis achieves two advantages: (1) the user makes only one decision, namely, in choosing the size of r and (2) there is at least a 95-percent probability that each cluster contains a nonrandom grouping. The latter advantage results in dividing the data into subsets that represent meaningful classifications.



NOTE: Percent of hemispherical surface contained in sphere of radius $b = 2 \sin(\frac{r}{2})$ about the point P is $(1 - \cos r)$.

FIGURE 1. - Spherical counting cell.

Application to the Sphere

For vectorial data, the sphere is divided into 800 equal area cells and for axial data, the hemisphere is divided into 400 equal area cells. The user must specify whether his data are vectorial or axial, since this information influences the randomness test described earlier. A value must be chosen for r in degrees and the value of k is determined by the randomness test. Then, for each point, the observations contained in a sphere of radius $b = 2 \sin(\frac{r}{2})$ about that point are counted (see fig. 1). Each point for

which this count is k or more is called dense. However, no cell may contain more than one dense point. This restriction on the number of dense points is introduced to minimize the computational effort involved in the analysis of large samples. Points in a cell containing a dense point belong to the cluster which contains that dense point. From this point on, the algorithm proceeds as described in the previous two sections.

The value of r is given in degrees and then converted to an Euclidean distance to provide the user with a better idea of the size of the counting cell being used (see fig. 1).

The Objective Function

Different values of r produce different partitions of the data. In some cases knowledge of the structure of the partitions formed as r assumes different values may not be sufficient. It may be desirable to select that partition which is "best" in the sense that it minimizes or maximizes some variable associated with the partitions. For example, a minimum variance partition may be most desirable. HYBMODE evaluates the function:

$$\psi = \sum_{i=1}^M \sum_{j=1}^{N_i} \|C_i - X_i^j\|^2 + \sum_{i=1}^{M-1} \sum_{j=i+1}^M \|C_i - C_j\|^2$$

where M is the number of clusters in the partition,

N_i is the number of observations in the i^{th} cluster,

C_i is the mean of the i^{th} cluster,

X_i^j is the j^{th} datum of the i^{th} cluster,

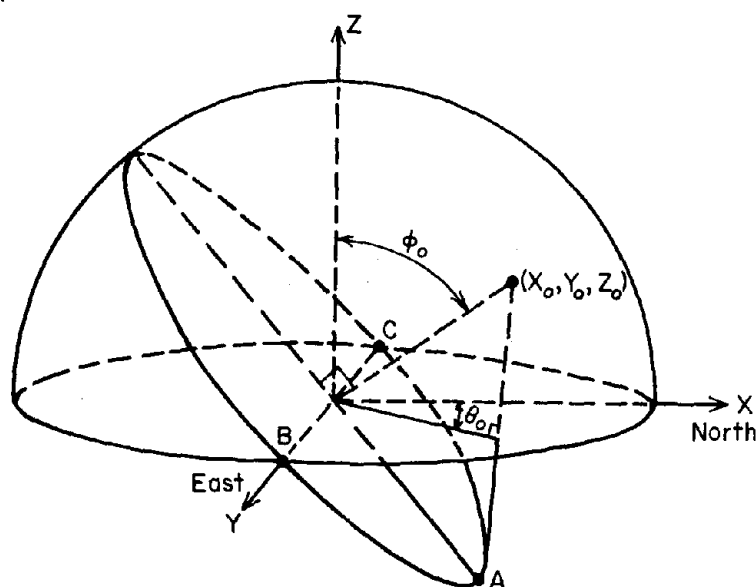
and $\|a-b\|$ denotes the Euclidean distance from a to b .

Note that the definition of "best" employed here is subjectively determined and implies a prior knowledge of the distribution of the data. The function given above has, however, performed well for the several examples of actual and hypothetical data analyzed by the authors. The hypothetical data consist of several artificially generated hemispherically normal (1, appendix D) clusters. These results are provided in the program description under the heading "example output."

Application to Fracture Orientations

When the attitude of a rock fracture is measured, the values of azimuth of the dip and dip (see fig. 2) give the attitude of a plane which approximates the fracture surface. Now, given any plane in three-dimensional Euclidean space, there is a line perpendicular to that plane (a normal to the plane) which passes through the coordinate origin (0,0,0). This normal must intersect the unit sphere (that is, the set of all points (X,Y,Z) such that

4



ϕ_o : dip of plane ABC

θ_o : azimuth of dip of plane ABC

$X_o = \sin \phi_o \cos \theta_o$

$Y_o = \sin \phi_o \sin \theta_o$

$Z_o = \cos \phi_o$

FIGURE 2. - Representation of fracture orientations by points on the unit sphere.

CDC 6400 computer. It is 803 cards long. When dimensioned to handle 500 data points, 75,600 words of memory are required to load. The main program flow chart is provided in figure 3. The two subroutines POLARC and SPRPAG have been adapted from another Bureau of Mines publication (3). Subroutine SORT has been adapted from a publication of the Kansas State Geological Survey (4).

HYBMODE Main Program

Calls input and initialization routines, sorts data into patches, and defines randomness test for spherical counting cell. Clusters dense points, allocates non-dense points, and outputs results with value of objective function

Subroutine CHANGE (M, N)

Points belonging to M^{th} dense point are reallocated to N^{th} dense point.

Subroutine ALLOC

Allocates each nondense point to the nearest dense point.

$X^2 + Y^2 + Z^2 = 1$) at two distinct points: (X_1, Y_1, Z_1) , (X_2, Y_2, Z_2) , where either $Z_1 \geq 0$ or $Z_2 \geq 0$.

For one of these two points, the following relationship holds: $X_1 = \sin \phi_1 \cos \theta_1$, $Y_1 = \sin \phi_1 \sin \theta_1$, $Z_1 = \cos \phi_1$, where ϕ_1 and θ_1 are the dip and azimuth of the dip respectively, of the plane of approximation (for axial data, $Z_1 \geq 0$). Since the set of all such points (X_1, Y_1, Z_1) comprises the sample that is actually analyzed, no distinction is made between the planes approximating fracture surfaces and the fracture surfaces themselves.

PROGRAM DESCRIPTION

Summary of Subroutines of HYBMODE

The program HYBMODE is written in Fortran IV and is designed to run on a

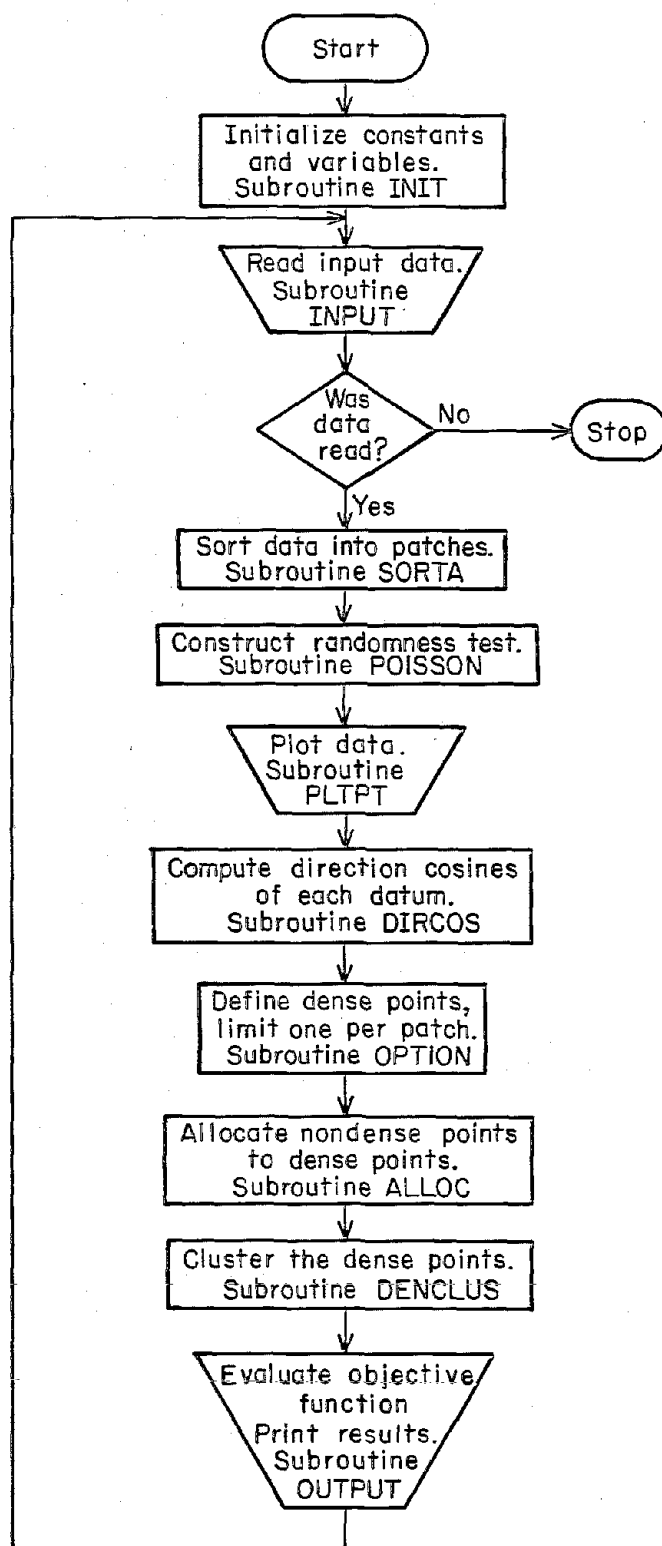


FIGURE 3. - Flow chart of main program.

Subroutine POLARC

Prints "*" at the center and at every 10° interval around the boundary of the output graph. Places N, E, S, W at 0° , 90° , 180° , 270° , respectively, and prints assembled page.

Subroutine SPRPAG (IX,IY,DIN,AZN)

Calculates page coordinates (IX,IY) of a point with spherical coordinates (I,AZN,DIN).

Function DIST (I, J)

Computes distance from I^{th} observation to J^{th} observation.

Function DIST2 (K, J)

Computes distance from K^{th} dense point to J^{th} dense point.

Function DIST1 (KK, JJ)

Computes distance from KK^{th} observation to JJ^{th} dense point.

Subroutine SORTA (KKL, LL3)

Sorts data into patches.

Subroutine OUTPUT

Prints contents of each cluster and evaluates the objective function.

Subroutine INPUT

Reads input data and program options.

Subroutine POISSON

Formulates randomness test for spherical counting cell.

Subroutine OPTION (KK1)

Defines dense points.

Subroutine BPLTPT (NN,K)

Loads arrays CU1, CU2 with observations belonging to NN^{th} dense point.
There are K such points.

Subroutine PCTPLT (KK1)

Plots RLEVEL(J) at the projected (polar equal area) midpoint of patch J.

Subroutine DIRCOS (A,D,N,SL,SM,SN)

Calculates direction cosines of points, given azimuths of dip and dips.

Subroutine SPHRPT (X,Y,Z,D,A,R,)

Computes dip and azimuth of the dip of a point, given its (X,Y,Z) coordinates.

Subroutine DENCLUS

Clusters the dense points.

Subroutine PLTPT (A,D,N)

Given the azimuths and dips of a set of points, plots them (polar equal area projection).

Subroutine INIT (RADIUS)

Initializes constants and subscripted variables.

Subroutine SUMCOS

Computes (X,Y,Z) coordinates of resultant of cluster CU1, CU2.

Subroutine SORT (X,Y,N)

Sorts the N elements of X and Y into decreasing order of X.

Function DIST3(K, J)

Computes distance from the negative of the K^{th} point to the J^{th} point.

Subroutine XLEVEL (KK1)

Computes density of each cell.

Description of Output Produced by HYBMODE

The density (percent of sample) in each patch is computed and plotted (polar equal area projection) at the projected midpoint of the patch. Plots of the sample, the dense points, and the contents of each cluster are provided. The mean of each cluster is also computed. A summary of the above results and the values of the objective function corresponding to the various radii (RDIS) are also provided in the computer output.

Input Instructions

The data deck structure for program HYBMODE is given below:

<u>Card No.</u>	<u>Columns</u>	<u>Contents</u>	<u>Format</u>
1	1-80	HED	8A10
2	1-5	NOBS	
2	6-10	LANS	
2	11-15	ISPHER	
2	16-27	RDIS	
2	28-39	R1	
2	40-51	R2	3I5, 3F12.5 12F5.0
3-NOBS/8=K-1	1-80	AZ(I), DIP(I) I=1, NOBS	
K	1-8	CONTINUE	A10
K+1	1-5	LANS	
K+1	6-17	RDIS	
K+1	18-29	R1	
K+1	30-41	R2	I5, 3F12.5
K+2	1-8	CONTINUE	A10
K+3	-	LANS	-
etc.	-	etc.	-

The user may select several option lists by use of the CONTINUE card.

More than one data deck may be submitted at a time by assembling them in order in which they are to be run. They need not be separated by any special card.

All observations must be coded in the form (θ, ϕ) where θ denotes azimuth of the dip and ϕ denotes the dip. The spherical coordinates of this observation when plotted on the unit sphere are (R, θ, ϕ) . The spherical coordinate system is presented in figure 2.

Glossary of Frequently Used Variables

Variable name	Definition
HED.....	Heading identifying data.
NOBS.....	Number of observations in data deck.
ISPHER.....	=1, Vectorial data; $\neq 1$, Axial data.
RDIS.....	Radius of spherical counting cell.
AZ(I).....	Azimuth of dip of I th observation (degrees).
DIP(I).....	Dip of I th observation (degrees).
PCTSURF.....	Percentage of hemispherical (ISPHER=0) or spherical (ISPHER=1) surface contained in a spherical counting cell.
KPCUT.....	Randomness test value.
NDENSE.....	Number of points whose spherical counting cells contain KPCUT or more points.
SLD(I), SMD(I), SND(I)...	The (X,Y,Z) coordinates respectively of the I th dense point.
B(J).....	Index of the dense point to which the J th observation belongs.
SL(K), SM(K), SN(K).....	(X,Y,Z) coordinates of the point whose spherical coordinates are (1, AZ(K), DIP(K)).
LPATCH(K).....	Number of observations lying in patches 1 through K inclusive.
KBAND(K).....	Number of the band containing patch #K.
IBND(K).....	Number of patches in band #K.
DANG(K).....	Range of possible dip values for points in K th band is: $DANG(K-L) \leq DIP < DANG(K)$.
ICUT.....	Number of points with Dip > 90°.
LANS.....	=1 An observation is counted among those points in sphere of radius RDIS about point Y if either the distance from X to Y or the distance from -X to Y is less than or equal to RDIS. $\neq 1$ An observation X is counted among those points in sphere of radius RDIS about point Y if the distance from X to Y is less than or equal to Y.
R1.....	Radius of data plot and dense point plot. If R1 = 0, these plots are not provided.
R2.....	Radius of density plot. If R2=0, this plot is not provided.

PROGRAM LISTING

PROGRAM HYBMODE(TAPE5,OUTPUT,TAPE6=OUTPUT,TAPE7)	HYBMODE	1
COMMON/B1/ AZ(500),DIP(500),NOBS	HYBMODE	2
COMMON/B2/ NDENSE,KPCUT,IFLAG(500)	HYBMODE	3
COMMON/B3/ RDIS,ISPHER,LANS	HYBMODE	4
COMMON/B8/ SL(500),SM(500),SN(500)	HYBMODE	5
COMMON/B21/ R1,R2	HYBMODE	6
COMMON/B22/ IOP	HYBMODE	7
COMMON/B23/ PCTSUF,RDEG	HYBMODE	8
COMMON/B24/ MC,VARSUM4	HYBMODE	9
C*****	HYBMODE	10
C***** INITAILIZE CONSTANTS AND VARIABLES	HYBMODE	11
C*****	HYBMODE	12
CALL INIT	HYBMODE	13
99997 CALL SECOND(T1)	HYBMODE	14
C*****	HYBMODE	15
C***** READ INPUT DATA	HYBMODE	16
C*****	HYBMODE	17
CALL INPUT	HYBMODE	18
C*****	HYBMODE	19
C***** CONSTRUCT TEST FOR RANDOMNESS	HYBMODE	20
C*****	HYBMODE	21
CALL POISSON	HYBMODE	22
C*****	HYBMODE	23
C***** SORT DATA INTO PATCHES	HYBMODE	24
C***** DETERMINE DENSE POINTS(MAXIMUM OF ONE PER PATCH)	HYBMODE	25
C*****	HYBMODE	26
IF(IOP) 3000,3000,3001	HYBMODE	27
3000 IF(ISPHER - 1) 2,1,2	HYBMODE	28
1 K1=1	HYBMODE	29
K2=1	HYBMODE	30
GO TO 3	HYBMODE	31
2 K1=19	HYBMODE	32
K2=401	HYBMODE	33
3 CALL SORTA(K1,K2)	HYBMODE	34
IF(R2-6.0) 49,50,50	HYBMODE	35
50 CALL XLEVEL(K2)	HYBMODE	36
CALL INITR(R2)	HYBMODE	37
CALL PCTPLT(K2)	HYBMODE	38
49 IF(R1) 1000,1000,999	HYBMODE	39
999 CALL INITR(R1)	HYBMODE	40
CALL PLTPT(AZ,DIP,NOBS)	HYBMODE	41
IF(ICUT .GE. NOBS) GO TO 1001	HYBMODE	42
CALL PLTPT1(AZ,DIP,NOBS)	HYBMODE	43
1001 WRITE(6,900) NOBS	HYBMODE	44
900 FORMAT(//1X,*DATA PLOT(POLAR EQUAL AREA PROJECTION).*/	HYBMODE	45
1 1X,*THERE ARE*,15,1X,*POINTS IN THE SAMPLE.*/	HYBMODE	46
1000 WRITE(7,902)	HYBMODE	47
902 FORMAT(1H1,*SUMMARY OF RESULTS*//	HYBMODE	48
1 30X,*RANDOMNESS*,3X,*NO OF*,4X,*OBJECTIVE*,2X,*TIME(SECONDS).*/	HYBMODE	49
2 1X,*RDIS ISPHER LANS PCTSUF*,5X,*TEST*,5X,*CLUSTERS*,	HYBMODE	50
3 3X,*FUNCTION*,4X,*REQUIRED*///)	HYBMODE	51
CALL DIRCOS(AZ,DIP,NOBS,SL,SM,SN)	HYBMODE	52
3001 CALL OPTION(K2)	HYBMODE	53
C***** ALLOCATE EACH REMAINING POINT TO THE DENSE POINT NEAREST IT	HYBMODE	54
IF(NDENSE) 99997,99997,91	HYBMODE	55
91 CALL ALLOC	HYBMODE	56
C***** CLUSTER THE DENSE POINTS	HYBMODE	57
CALL DENCLUS	HYBMODE	58
C***** COMPUTE VALUE OF OBJECTIVE FUNCTION AND OUTPUT CLUSTERS	HYBMODE	59

CALL OUTPUT	HYBMODE	60
CALL SECOND(T2)	HYBMODE	61
TIME=T2-T1	HYBMODE	62
WRITE(6,901) NOBS,TIME	HYBMODE	63
901 FORMAT(1X,*TIME REQUIRED TO ANALYZE*,I5,1X,*DATA POINTS*,F7.3,1X,	HYBMODE	64
1 *SECONDS*)	HYBMODE	65
WRITE(7,911) RDEG,ISPHER,LANS,PCTSUF,KPCUT,MC,VARSUM4,TIME	HYBMODE	66
911 FORMAT(F5.1,I5,I8,F8.2,I10,I11,E14.3,F10.3)	HYBMODE	67
GO TO 99997	HYBMODE	68
END	HYBMODE	69
SUBROUTINE CHANGE(M,N)	CHANGE	1
C***** REALLOCATE POINTS BELONGING TO DENSE POINT NUMBER M TO DENSE	CHANGE	2
C***** POINT NUMBER N	CHANGE	3
COMMON/B1/ AZ(500),DIP(500),NOBS	CHANGE	4
COMMON/B7/ B(500)	CHANGE	5
INTEGER B	CHANGE	6
DO 1 NN=1,NOBS	CHANGE	7
IF(B(NN) .EQ. M) B(NN)=N	CHANGE	8
1 CONTINUE	CHANGE	9
RETURN \$ END	CHANGE	10
SUBROUTINE ALLOC	ALLOC	1
C***** ALLOCATE EACH POINT TO A DENSE POINT	ALLOC	2
COMMON/B1/ AZ(500),DIP(500),NOBS	ALLOC	3
COMMON/B2/ NDENSE,KPCUT,IFLAG(500)	ALLOC	4
COMMON/B7/ B(500)	ALLOC	5
INTEGER B	ALLOC	6
DIMENSION DIS(500)	ALLOC	7
DO 1 JJ=1,NOBS	ALLOC	8
IF(B(JJ)) 1,5,1	ALLOC	9
5 DO 2 KK=1,NDENSE	ALLOC	10
2 DIS(KK)=DIST1(JJ,KK)	ALLOC	11
DS=100.	ALLOC	12
DO 3 NN=1,NDENSE	ALLOC	13
IF(DIS(NN) .GE. DS) GO TO 3	ALLOC	14
4 DS=DIS(NN)	ALLOC	15
MINDEX=NN	ALLOC	16
3 CONTINUE	ALLOC	17
B(JJ)=MINDEX	ALLOC	18
1 CONTINUE	ALLOC	19
RETURN \$ END	ALLOC	20
SUBROUTINE POLARC	POLARC	1
C POLARC * * * * *	POLARC	2
C DRAWS AND LABELS AXES AND CIRCLE SURROUNDING OUTPUT GRAPH.	POLARC	3
C PLACES AN * AT EVERY 10 DEGREES AROUND CIRCLE CIRCUMFERENCE,WITH	POLARC	4
C N,E,S,W AT 0,90,180,270 DEGREES RESPECTIVELY.	POLARC	5
C * * CALLS- SPRPAG * * * * *	POLARC	6
C * * * * *	POLARC	7
COMMON/B4/ NXMID,NYMID,NX,NY,XCONV,YCONV	POLARC	8
COMMON/B5/ LPAGE(130,78)	POLARC	9
DIMENSION LDIR(4)	POLARC	10
DATA LASTER/1H*/XINC/10.0/,LOIR/1HN,1HS,1HE,1HW/	POLARC	11
DATA LBLANK/1H /,Q90/90.0/	POLARC	12
NX1=NX-1	POLARC	13
ANGL=0.0	POLARC	14
DO 200 I=1,36	POLARC	15
CALL SPRPAG(IX,IY,Q90,ANGL)	POLARC	16
LPAGE(IX,IY)=LASTER	POLARC	17
200. ANGL=ANGL+10.	POLARC	18
LPAGE(NXMID,NYMID)=LASTER	POLARC	19

```

C      LABEL N,S,E,W AT APPROPRIATE POSITIONS
600  LPAGE(NXMID,NY)=LDIR(1)
      LPAGE(NXMID,1)=LDIR(2)
      LPAGE(NX,NYMID)=LDIR(3)
      LPAGE(1,NYMID)=LDIR(4)
C      PRINT THE COMPLETE ASSEMBLED PAGE IMAGE,ROW BY ROW
C      **NOTE** THE INDEX K MUST GO BACKWARDS BECAUSE THE ASSUMED
C      COORDINATE ORIGIN IS AT LOWER LEFT HAND CORNER OF PAGE.
      DO 700 J=1,NY
      K=NY-J+1
700  WRITE(6,2000) (LPAGE(I,K),I=1,NX)
2000 FORMAT(121A1)
      DO 199 J1=1,73
      DO 199 J2=1,121
199  LPAGE(J2,J1)=LBLANK
      RETURN
      END
      SUBROUTINE SPRPAG(IX,IY,DIN,AZN)
C  SPRPAG * * * * *
C  GIVEN HEMISPHERE COORDINATES (DIN,AZN),SPRPAG RETURNS NEAREST
C  PAGE COORDINATES (IX,IY). IF OUTSIDE PAGE,MOVES IX OR IY TO
C  CLOSEST POINT ON EDGE OF PAGE
      COMMON/B4/ NXMID,NYMID,NX,NY,XCONV,YCONV
      COMMON/B12/ DEGRAD,RADEG
      ANGLR=AZN*DEGRAD
C  THE NEXT 3 STATEMENTS PERFORM EQUAL-AREA PROJECTION
100  XYT=127.2798*SIN(DEGRAD*DIN/2.0)
      NDUM=XYT*SIN(ANGLR)*XCONV+0.5
      JDUM=XYT*COS(ANGLR)*YCONV+0.5
200  IX=NXMID+NDUM
C      BRING X INDEX IN RANGE IF IT IS OUTSIDE.
      IF(IX.LT.1) IX=1
      IF(IX.GT.NX) IX=NX
      IY=NYMID+JDUM
C      BRING Y INDEX IN RANGE IF IT IS OUTSIDE.
      IF(IY.LT.1) IY=1
      IF(IY.GT.NY) IY=NY
      RETURN
      END
      FUNCTION DIST(I,J)
C***** DIST = DISTANCE FROM PT NUMBER I TO PT NUMBER J
      COMMON/B8/ SL(500),SM(500),SN(500)
      DIST=(SL(I)-SL(J))**2 + (SM(I)-SM(J))**2 + (SN(I)-SN(J))**2
      RETURN $ END
      FUNCTION DIST2(K,J)
C***** DIST2 = DISTANCE FROM DENSE POINT NUMBER K TO DENSE PCINT
C***** NUMBER J
      COMMON/B6/ SLD(500),SMD(500),SND(500)
      DIST2=(SLD(K)-SLD(J))**2+(SMD(K)-SMD(J))**2+(SND(K)-SND(J))**2
      RETURN $ END
      FUNCTION DIST1(KK,JJ)
C***** DIST1 = DISTANCE FROM POINT NUMBER KK TO DENSE POINT NUMBER
C***** JJ
      COMMON/B6/ SLD(500),SMD(500),SND(500)
      COMMON/B8/ SL(500),SM(500),SN(500)
      DIST1=(SL(KK)-SL(JJ))**2+(SM(KK)-SM(JJ))**2+(SN(KK)-SN(JJ))**2
      RETURN $ END
      SUBROUTINE SORTA(KK1,LL3)
C***** SORTS DATA INTO PATCHES. IPATCH(J) IS THE LARGEST INDEX I

```

```

C***** SUCH THAT (A(I),D(I)) IS IN PATCH NUMBER J. IF PATCH NUMBER
C***** J IS EMPTY, IPATCH(J) = IPATCH(J-1). IF(ISPHER = 1, THEN
C***** KK1=LL3-1. IF ISPHER NE 1, KK1=19, LL3=401, AND
C***** BANDS 19 THROUGH 36 AND CELLS 401 THROUGH 800 CONTAIN ALL
C***** THE DATA. IF ISPHER = 1 THEN THERE ARE DATA POINTS WITH
C***** DIP GREATER THAN 90 DEGREES IN WHICH CASE BANDS 1 THROUGH
C***** 19 AND PATCHES 1 THROUGH 400 CONTAIN DATA ALSO.
      COMMON/B1/ A(500),D(500),NOBS
      COMMON/B9/ IPATCH(800),KBAND(800)
      COMMON/B11/ IBND(36)
      COMMON/B16/ DANG(37)
      DATA NB/36/
      REAL KANG
      DO 9 I=1,800
      9 IPATCH(I)=0

C***** ARRANGE DATA IN DECREASING ORDER OF DIP
      NOBS1=NOBS-1
      CALL SORT(D,A,NOBS)
C
C***** ARRANGE THE POINTS IN EACH BAND IN INCREASING ORDER OF AZIMUTH
      M=1
      DO 93 L=KK1,NB
      IF(M .EQ. NOBS) GO TO 8888
      94 CONTINUE
      DO 92 J=M,NOBS1
      J1=J+1
      IF(D(J) .GE. DANG(L+1)) GO TO 8884
      8885 M=J
      GO TO 93
      8884 DO 90 K=J1,NOBS
      IF(D(K) .GE. DANG(L+1)) GO TO 8886
      8887 M=J+1
      GO TO 94
      8886 IF(A(J)-A(K)) 90,90,91
      91 TMP=A(J)
      A(J)=A(K)
      A(K)=TMP
      TMP=D(J)
      D(J)=D(K)
      D(K)=TMP
      90 CONTINUE
      M=M+1
      92 CONTINUE
      93 CONTINUE
      8888 CONTINUE

C***** DETERMINE WHICH PATCHES CONTAIN DATA
      II=LL3-1
      LP=0
      KK=0
      ICP=1
      DO 87 J=KK1,NB
      II=II+KK
      IBJ=IBND(J)
      SORTA 3
      SORTA 4
      SORTA 5
      SORTA 6
      SORTA 7
      SORTA 8
      SORTA 9
      SORTA 10
      SORTA 11
      SORTA 12
      SORTA 13
      SORTA 14
      SORTA 15
      SORTA 16
      SORTA 17
      SORTA 18
      SORTA 19
      SORTA 20
      SORTA 21
      SORTA 22
      SORTA 23
      SORTA 24
      SORTA 25
      SORTA 26
      SORTA 27
      SORTA 28
      SORTA 29
      SORTA 30
      SORTA 31
      SORTA 32
      SORTA 33
      SORTA 34
      SORTA 35
      SORTA 36
      SORTA 37
      SORTA 38
      SORTA 39
      SORTA 40
      SORTA 41
      SORTA 42
      SORTA 43
      SORTA 44
      SORTA 45
      SORTA 46
      SORTA 47
      SORTA 48
      SORTA 49
      SORTA 50
      SORTA 51
      SORTA 52
      SORTA 53
      SORTA 54
      SORTA 55
      SORTA 56
      SORTA 57
      SORTA 58
      SORTA 59
      SORTA 60
      SORTA 61

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DO 87 K=1,IBJ	SORTA	62
IF(LP .EQ. NOBS) GO TO 88	SORTA	63
KK=K	SORTA	64
KANG=FLOAT(K)*360./FLOAT(IBND(J))	SORTA	65
IF(K .EQ. IBND(J)) KANG=360.5	SORTA	66
DO 86 L=1CP,NOBS	SORTA	67
IF(A(L) .GT. KANG .OR. D(L) .LT. DANG(J+1)) GO TO 79	SORTA	68
LP=LP+1	SORTA	69
IF(LP .NE. NOBS) GO TO 86	SORTA	70
79 IPATCH(II+K)=LP	SORTA	71
IOP=LP+1	SORTA	72
L=II+K+1	SORTA	73
GO TO 87	SORTA	74
86 CONTINUE	SORTA	75
87 CONTINUE	SORTA	76
88 IF(L .EQ. 801) RETURN	SORTA	77
DO 89 J=L,800	SORTA	78
89 IPATCH(J)=NOBS	SORTA	79
RETURN \$ END	SORTA	80
SUBROUTINE OUTPUT	OUTPUT	1
C*****	OUTPUT	2
C***** PRINTS CONTENTS OF CLUSTERS AND EVALUATES OBJECTIVE FUNCTION	OUTPUT	3
C*****	OUTPUT	4
COMMON/B2/ NDENSE,KPCUT,IFLAG(500)	OUTPUT	5
COMMON/B3/ RDIS,ISPHER,LANS	OUTPUT	6
COMMON/B13/ KOU	OUTPUT	7
COMMON/B14/ CU1(500),CU2(500)	OUTPUT	8
COMMON/B15/ SLL(500),SMM(500),SNN(500)	OUTPUT	9
COMMON/B19/ SX,SY,SZ	OUTPUT	10
COMMON/B21/ R1,R2	OUTPUT	11
COMMON/B23/ PCTSUF,RDEG	OUTPUT	12
COMMON/B24/ MC,VARSUM4	OUTPUT	13
COMMON/B26/ ICUT	OUTPUT	14
DIMENSION CGX(50),CGY(50),CGZ(50)	OUTPUT	15
DATA IPLUS/IH+I	OUTPUT	16
MC=0	OUTPUT	17
VAR=0.0	OUTPUT	18
VARA=0.0	OUTPUT	19
WRITE(6,907)	OUTPUT	20
907 FORMAT(IH1,*OUTPUT OF CLUSTERS, CLUSTER MEANS*)	OUTPUT	21
DO 30 MJ=1,NDENSE	OUTPUT	22
IF(IFLAG(MJ) .NE. MJ) GO TO 30	OUTPUT	23
VAR1=0.0	OUTPUT	24
MC=MC+1	OUTPUT	25
IF(MC-1) 1001,1000,1001	OUTPUT	26
1000 WRITE(6,908) MC	OUTPUT	27
908 FORMAT(//* CLUSTER NUMBER*,I5///)	OUTPUT	28
GO TO 1002	OUTPUT	29
1001 WRITE(6,910) MC	OUTPUT	30
910 FORMAT(IH1*CLUSTER NUMBER*,I5///)	OUTPUT	31
1002 CONTINUE	OUTPUT	32
C***** PUT POINTS BELONGING TO DENSE POINT NUMBER MJ INTO ARRAYS	OUTPUT	33
C***** CU1 AND CU2(AZIMUTH OF DIP AND DIP RESPECTIVELY). KOU IS	OUTPUT	34
C***** RETURNED TO THE CALLING PROGRAM AND IS THE NUMBER OF SUCH	OUTPUT	35
C***** POINTS.	OUTPUT	36
CALL BPLTPT(MJ,KOU)	OUTPUT	37
XKOU=FLOAT(KOU)	OUTPUT	38
WRITE(6,900) (KK,CU1(KK),CU2(KK),KK=1,KOU)	OUTPUT	39
900 FORMAT(5X,*NUM*,5X,*AZIMUTH *,*INCLINATION*,/(I8,2F12.2))	OUTPUT	40

C***** COMPUTE DIRECTION COSINES	OUTPUT	41
61 CALL DIRCOS(CU1,CU2,KOU,SLL,SMM,SNN)	OUTPUT	42
C***** CALCULATE RESULTANT BY ADDING THE DIRECTION COSINES	OUTPUT	43
CALL SUMCOS	OUTPUT	44
C***** DETERMINE SPHERICAL COORDINATES FOR RESULTANT AND MEAN	OUTPUT	45
CALL SPHRPT(SX,SY,SZ,DP,AT,R)	OUTPUT	46
WRITE(6,48) AT,DP	OUTPUT	47
48 FORMAT(///1X,*MEAN*/1X,*AZIMUTH*,F7.2,1X,*DEG*/1X,*INCLINATION*,	OUTPUT	48
1 F7.2,1X,*DEG*)	OUTPUT	49
WRITE(6,906) R,SX,SY,SZ	OUTPUT	50
906 FORMAT(1X,*RESULTANT AND ITS COMPONENTS - R,SX,SY,SZ,*/ 4F12.5)	OUTPUT	51
SUM2=0.0	OUTPUT	52
AL1=CGX(MC)=SX/XKOU	OUTPUT	53
AM1=CGY(MC)=SY/XKOU	OUTPUT	54
AN1=CGZ(MC)=SZ/XKOU	OUTPUT	55
WRITE(6,911) AL1,AM1,AN1	OUTPUT	56
911 FORMAT(1X,*CENTER OF GRAVITY - (X,Y,Z) COORDINATES*/	OUTPUT	57
1 3F10.4)	OUTPUT	58
DO 10 LJ=1,KOU	OUTPUT	59
DIS=(SQRT((AL1-SLL(LJ))**2 + (AM1-SMM(LJ))**2 + (AN1-SNN(LJ))**2))	OUTPUT	60
1**2	OUTPUT	61
SUM2=SUM2+DIS	OUTPUT	62
10 CONTINUE	OUTPUT	63
VARA=VARA+SUM2	OUTPUT	64
IF(R1) 31,31,2001	OUTPUT	65
2001 CALL PLTPT(CU1,CU2,KOU)	OUTPUT	66
IF(ICUT .GE. KOU) GO TO 31	OUTPUT	67
IF(ICUT) 2002,2002,2003	OUTPUT	68
2003 WRITE(6,912) MC,KOU,RDEG	OUTPUT	69
2002 CALL PLTPT1(CU1,CU2,KOU)	OUTPUT	70
31 WRITE(6,912) MC,KOU,RDEG	OUTPUT	71
30 CONTINUE	OUTPUT	72
VARSUM2=0.0	OUTPUT	73
912 FORMAT(1X,*CLUSTER NO.*/,15,1X,	OUTPUT	74
1 *CONTAINS*/,15,1X,*POINTS.*/1X,	OUTPUT	75
2 *FOR THIS ANALYSIS, RDIS =*,F7.2)	OUTPUT	76
VARSUM2=0.0	OUTPUT	77
IF(MC .EQ. 1) GO TO 50	OUTPUT	78
MC1=MC-1	OUTPUT	79
DO 40 LJ=1,MC1	OUTPUT	80
LJ1=LJ+1	OUTPUT	81
DO 40 MJ=LJ1,MC	OUTPUT	82
DIS=(CGX(LJ)-CGX(MJ))**2 + (CGY(LJ)-CGY(MJ))**2 +	OUTPUT	83
1 (CGZ(LJ)-CGZ(MJ))**2	OUTPUT	84
VARSUM2=VARSUM2+DIS	OUTPUT	85
40 CONTINUE	OUTPUT	86
50 VARSUM4=VARSUM2+VARA	OUTPUT	87
WRITE(6,905) VARSUM4	OUTPUT	88
905 FORMAT(1X,*OBJECTIVE FUNCTION =*,F12.3)	OUTPUT	89
RETURN * END	OUTPUT	90
SUBROUTINE INPUT	INPUT	1
C***** READ INPUT DATA	INPUT	2
COMMON/B1/ AZ(500),DIP(500),NOBS	INPUT	3
COMMON/B3/ RDIS,ISPHER,LANS	INPUT	4
COMMON/B21/ R1,R2	INPUT	5
COMMON/B22/ IOP	INPUT	6
DIMENSION HED(8)	INPUT	7
READ(5,900) HED	INPUT	8
900 FORMAT(8A10)	INPUT	9

IF(EOF,5) 1000,1001	INPUT	10
1001 LL=1	INPUT	11
IF(HED(1) .EQ. 10HCONTINUE) LL=2	INPUT	12
GO TO (7002,7000),LL	INPUT	13
7002 READ(5,906) NOBS,LANS,ISPHER,RDIS,R1,R2	INPUT	14
1 ,(AZ(1),DIP(1),I=1,NOBS)	INPUT	15
906 FORMAT(3I5,3F12.5/(12F5.0))	INPUT	16
WRITE(6,907) HED,NOBS,LANS,ISPHER,RDIS,R1,R2	INPUT	17
1 ,(AZ(1),DIP(1),I=1,NOBS)	INPUT	18
907 FORMAT(1H1/8A10//	INPUT	19
1 1X,*NOBS =*,15//	INPUT	20
2 1X,*LANS =*,15//	INPUT	21
3 1X,*ISPHER =*,15//	INPUT	22
4 1X,*RDIS =*,F6.1//	INPUT	23
5 1X,*RADIUS OF POINT PLOT =*,F6.1//	INPUT	24
6 1X,*RADIUS OF DENSITY PLOT =*,F6.1//	INPUT	25
7 1X,*AZIMUTH OF THE DIP AND DIP OF THE DATA POINTS*//	INPUT	26
8 (12F5.0))	INPUT	27
IOP=0	INPUT	28
RETURN	INPUT	29
7000 READ(5,908) LANS,RDIS	INPUT	30
908 FORMAT(15,F12.5)	INPUT	31
WRITE(6,909) LANS,RDIS	INPUT	32
909 FORMAT(1H1,*FOR NEXT ANALYSIS OF SAMPLE*//	INPUT	33
1 1X,*LANS =*,15//	INPUT	34
2 1X,*RDIS =*,F6.1//)	INPUT	35
CALL INITI(4.0)	INPUT	36
IOP=1	INPUT	37
GO TO 1002	INPUT	38
1000 STOP	INPUT	39
1002 CONTINUE	INPUT	40
RETURN \$ END	INPUT	41
SUBROUTINE POISSON	POISSON	1
C***** CONSTRUCT TEST FOR RANDOMNESS - SPHERICAL COUNTING CELL MUST	POISSON	2
C***** CONTAIN AT LEAST KPCUT POINTS FOR A SIGNIFICANT(95)	POISSON	3
C***** CONCENTRATION TO BE PRESENT	POISSON	4
COMMON/B1/ AZ(500),DIP(500),NOBS	POISSON	5
COMMON/B2/ NDENSE,KPCUT,IFLAG(500)	POISSON	6
COMMON/B3/ RDIS,ISPHER,LANS	POISSON	7
COMMON/B12/ DEGRAD,RADEG	POISSON	8
COMMON/B23/ P,RDEG	POISSON	9
RDEG=RDIS*DEGRAD	POISSON	10
FN=FLOAT(NOBS)	POISSON	11
PCTSURF=1.0-COS(RDEG)	POISSON	12
IF(ISPHER .EQ. 1) PCTSURF=0.5*PCTSURF	POISSON	13
A=FN*PCTSURF	POISSON	14
P=100.0*PCTSURF	POISSON	15
WRITE(6,910) RDIS,P	POISSON	16
910 FORMAT(1X,*FOR RDIS =*,F6.2,1X,*PERCENTAGE OF SURFACE AREA IS*,	POISSON	17
1 F6.2)	POISSON	18
RDIS=4.0*(SIN(RDEG/2.0))**2	POISSON	19
RDEG=RDEG*RADEG	POISSON	20
EFAC=EXP(-A)	POISSON	21
SUM=EFAC	POISSON	22
FAC=1.0	POISSON	23
DO 876 N=1,1000	POISSON	24
FIN=N	POISSON	25
FAC=FAC*A/FIN	POISSON	26
PROB=EFAC*FAC	POISSON	27

SUM=SUM+PROB	POISSON	28
TEST=1.0-SUM	POISSON	29
IF(TEST - 0.05) 875,876,876	POISSON	30
876 CONTINUE	POISSON	31
875 KPCUT=FIN	POISSON	32
WRITE(6,901) KPCUT,RDIS	POISSON	33
901 FORMAT(1X,*,A POINT X IS DENSE IF THERE ARE*,15,1X,*,OBSERVATIONS*/	POISSON	34
1 * WHOSE EUCLIDEAN DISTANCE FROM X IS LESS THAN*,E10.2,*,*/	POISSON	35
2)	POISSON	36
RETURN	POISSON	37
END	POISSON	38
SUBROUTINE OPTION(KK1)	OPTION	1
C***** BEGINNING WITH PATCH NUMBER KK1, EXAMINE EACH POINT TO SEE	OPTION	2
C***** IF IT IS DENSE	OPTION	3
COMMON/B1/ AZ(500),DIP(500),NOBS	OPTION	4
COMMON/B2/ NDENSE,KPCUT,IFLAG(500)	OPTION	5
COMMON/B3/ RDIS,ISPHER,LANS	OPTION	6
COMMON/B6/ SLD(500),SMD(500),SND(500)	OPTION	7
COMMON/B7/ B(500)	OPTION	8
COMMON/B8/ SL(500),SM(500),SN(500)	OPTION	9
COMMON/B9/ LPATCH(800),KBAND(800)	OPTION	10
COMMON/B11/ IBND(36)	OPTION	11
COMMON/B12/ DEGRAD,RADEG	OPTION	12
COMMON/B14/ CUI(500),CU2(500)	OPTION	13
COMMON/B21/ R1,R2	OPTION	14
COMMON/B26/ ICUT	OPTION	15
INTEGER B	OPTION	16
DATA IPLUS/1H+ /	OPTION	17
KOUNT=1	OPTION	18
KS=1	OPTION	19
LANS1=LANS-1	OPTION	20
IPRE=0	OPTION	21
DO 10 KK=KK1,800	OPTION	22
N1=LPATCH(KK)	OPTION	23
IF(N1 - IPRE) 104,104,100	OPTION	24
100 DO 11 JJ=KS,N1	OPTION	25
ISUM=0	OPTION	26
DO 12 MM=1,NOBS	OPTION	27
FD=DIST(JJ,MM)	OPTION	28
IF(LANS1) 7,9,7	OPTION	29
9 FDI=DIST3(JJ,MM)	OPTION	30
IF(FDI-RDIS) 6,6,7	OPTION	31
7 IF(FD-RDIS) 6,6,12	OPTION	32
6 ISUM=ISUM+1	OPTION	33
IF(ISUM-KPCUT) 12,8,8	OPTION	34
8 CONTINUE	OPTION	35
C***** IF PATCH NUMBER KK CONTAINS A DENSE POINT, STORE THE	OPTION	36
C***** DIRECTION COSINES OF THE POINT IN (SLD,SMD,SND)	OPTION	37
SLD(KOUNT)=SL(JJ)	OPTION	38
SMD(KOUNT)=SM(JJ)	OPTION	39
SND(KOUNT)=SN(JJ)	OPTION	40
CUI(KOUNT)=AZ(JJ)	OPTION	41
CU2(KOUNT)=DIP(JJ)	OPTION	42
C***** ALLOCATE ALL OTHER POINTS IN THE PATCH TO THE DENSE POINT	OPTION	43
DO 1001 JM=KS,N1	OPTION	44
1001 B(JM)=KOUNT	OPTION	45
KOUNT=KOUNT+1	OPTION	46
GO TO 104	OPTION	47
12 CONTINUE	OPTION	48

11 CONTINUE	OPTION	49
104 CONTINUE	OPTION	50
KS=LPATCH(KK)+1	OPTION	51
IPRE=N1	OPTION	52
10 CONTINUE	OPTION	53
NDENSE=KOUNT-1	OPTION	54
IF(NDENSE) 90,90,91	OPTION	55
C***** NDENSE IS THE NUMBER OF DENSE POINTS	OPTION	56
91 IF(R1) 90,90,1999	OPTION	57
1999 CALL PLTPT(CU1,CU2,NDENSE)	OPTION	58
IF(ICUT .GE. NDENSE) GO TO 90	OPTION	59
IF(ICUT) 92,92,93	OPTION	60
93 WRITE(6,900) NDENSE	OPTION	61
92 CALL PLTPT(CU1,CU2,NDENSE)	OPTION	62
90 WRITE(6,900) NDENSE	OPTION	63
900 FORMAT(/,1X,*THERE ARE*,15,1X,*DENSE POINTS.*)	OPTION	64
RETURN \$ END	OPTION	65
SUBROUTINE BPLTPT(NN,K)	BPLTPT	1
C***** POINTS BELONGING TO DENSE POINT NN ARE PUT INTO ARRAYS CU1 CU2	BPLTPT	2
COMMON/B1/ AZ(500),DIP(500),NOBS	BPLTPT	3
COMMON/B7/ B(500)	BPLTPT	4
COMMON/B14/ CU1(500),CU2(500)	BPLTPT	5
INTEGER B	BPLTPT	6
MM=NN	BPLTPT	7
KOUNT=1	BPLTPT	8
DO 3 M=1,NOBS	BPLTPT	9
IF(B(M)-MM) 3,4,3	BPLTPT	10
4 CU1(KOUNT)=AZ(M)	BPLTPT	11
CU2(KOUNT)=DIP(M)	BPLTPT	12
KOUNT=KOUNT+1	BPLTPT	13
3 CONTINUE	BPLTPT	14
K=KOUNT-1	BPLTPT	15
RETURN	BPLTPT	16
END	BPLTPT	17
SUBROUTINE PCTPLT(KK1)	PCTPLT	1
C***** PLOTS RLEVEL(J)(DENSITY OF PATCH J, I.E., PER CENT OF TOTAL SAMPLE	PCTPLT	2
C***** CONTAINED IN PATCH J) AT THE PROJECTED MIDPOINT OF PATCH	PCTPLT	3
C***** NUMBER J(POLAR EQUAL AREA PROJECTION).	PCTPLT	4
COMMON/B5/ LPAGE(130,79)	PCTPLT	5
COMMON/B9/ LPATCH(800),KBAND(800)	PCTPLT	6
COMMON/B10/ POS(800)	PCTPLT	7
COMMON/B11/ IBND(36)	PCTPLT	8
COMMON/B16/ DANG(37)	PCTPLT	9
COMMON/B20/ RLEVEL(800)	PCTPLT	10
COMMON/B21/ R1,R2	PCTPLT	11
DIMENSION NUM1(10),NUM(10)	PCTPLT	12
INTEGER O	PCTPLT	13
WRITE(6,905)	PCTPLT	14
905 FORMAT(1H1)	PCTPLT	15
DATA NUM1/1H ,1H1,1H2,1H3,1H4,1H5,1H6,1H7,1H8,1H9/,	PCTPLT	16
1 NUM/1H0,1H1,1H2,1H3,1H4,1H5,1H6,1H7,1H8,1H9/,LDOT/1H./	PCTPLT	17
WRITE(6,900)	PCTPLT	18
900 FORMAT(1HQ,*DENSITY PLOT - LOWER AND UPPER HEMISPHERES*//)	PCTPLT	19
DO 1 J=KK1,800	PCTPLT	20
IBJ=KBAND(J)	PCTPLT	21
AZN=(POS(J)-0.5)*360./FLOAT(IBND(IBJ))	PCTPLT	22
IBJ1=IBJ+1	PCTPLT	23
DIN=(DANG(IBJ)+DANG(IBJ1))/2.	PCTPLT	24
IF(DIN .GT. 90.0) DIN=180.0-DIN	PCTPLT	25

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CALL SPRPAG(IX,IY,DIN,AZN)
IF(DIN .LT. 81.0) GO TO 3033
IF(AZN .LT. 180.) IX=IX-2
IF(AZN .GT. 180.) IX=IX+2
3033 CONTINUE
IF(J .EQ. 1 .OR. J .EQ. 800) IY=IY-1
K=RLEVEL(J)*10000.+5.
M=K/1000
N=(K-(M*1000))/100
O=(K-M*1000-N*100)/10
LPAGE(IX-2,IY)=NUM1(M+1)
LPAGE(IX-1,IY)=NUM1(N+1)
IF(M .EQ. 0) LPAGE(IX-1,IY)=NUM1(N+1)
LPAGE(IX,IY)=LDOT
LPAGE(IX+1,IY)=NUM(O+1)
IF(M .EQ. 0 .AND. N .EQ. 0 .AND. O .EQ. 0) GO TO 2
GO TO 5
2 LPAGE(IX-2,IY)=NUM1(1)
LPAGE(IX-1,IY)=NUM1(1)
LPAGE(IX+1,IY)=NUM1(1)
5 IF(J .NE. 400 .AND. J .NE. 800) GO TO 1
IF(J .EQ. 800) GO TO 6
WRITE(6,901)
901 FORMAT(1X,'LOWER HEMISPHERE',//)
CALL POLARC
GO TO 7
6 WRITE(6,902)
902 FORMAT(1X,'UPPER HEMISPHERE',//)
CALL POLARC
7 WRITE(6,903)
903 FORMAT(1HR)
WRITE(6,905)
WRITE(6,904)
904 FORMAT(1HQ)
1 CONTINUE
WRITE(6,903)
RETURN
END
SUBROUTINE DIRCOS(A,D,N,SL,SM,SN)
C***** GIVEN THE SPHERICAL COORDINATES (1,A(I),D(I),I=1,N),
C***** RETURN THE CORRESPONDING (X,Y,Z) COORDINATES (SL(I),SM(I),
C***** SN(I),I=1,N)
COMMON/812/ DEGRAD,RADEG
DIMENSION A(N),D(N),SL(N),SM(N),SN(N)
DO 1 JJ=1,N
DD=D(JJ)*DEGRAD
AA=A(JJ)*DEGRAD
SL(JJ)=SIN(DD)*COS(AA)
SM(JJ)=SIN(DD)*SIN(AA)
SN(JJ)=COS(DD)
1 CONTINUE
RETURN
END
SUBROUTINE SPHRPT(X,Y,Z,D,A,R)
C***** GIVEN THE (X,Y,Z) COORDINATES OF A POINT, RETURN ITS
C***** SPHERICAL COORDINATES (R,D,A)
COMMON/812/ DEGRAD,RADEG
DATA PI2/6.2831853071795864769/
R=SQRT(X*X + Y*Y + Z*Z)

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PCTPLT 26
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DIRCOS 1
DIRCOS 2
DIRCOS 3
DIRCOS 4
DIRCOS 5
DIRCOS 6
DIRCOS 7
DIRCOS 8
DIRCOS 9
DIRCOS 10
DIRCOS 11
DIRCOS 12
DIRCOS 13
DIRCOS 14
DIRCOS 15
SPHRPT 1
SPHRPT 2
SPHRPT 3
SPHRPT 4
SPHRPT 5
SPHRPT 6

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IF(X .EQ. 0.0 .AND. Y .EQ. 0.0) GO TO 9395	SPHRPT	7
IF(Y) 9397,9396,9397	SPHRPT	8
9397 IF(X) 9398,9393,9398	SPHRPT	9
9398 A=ATAN2(Y,X)	SPHRPT	10
IF(A .LT. 0.0) A=A+PI2	SPHRPT	11
A=A*RADEG	SPHRPT	12
GO TO 9394	SPHRPT	13
9395 D=A*0.0	SPHRPT	14
RETURN	SPHRPT	15
9396 A=ABS((X/ABS(X)-1.0)*90.0)	SPHRPT	16
GO TO 9394	SPHRPT	17
9393 A=ABS((Y/ABS(Y)-2.0)*90.0)	SPHRPT	18
9394 D=ACOS(Z/R)*RADEG	SPHRPT	19
RETURN	SPHRPT	20
END	SPHRPT	21
SUBROUTINE DENCLUS	DENCLUS	1
C***** CLUSTER THE DENSE POINTS AS FOLLOWS - TWO DENSE POINTS	DENCLUS	2
C***** BELONG TO THE SAME CLUSTER IF THE DISTANCE BETWEEN THEM	DENCLUS	3
C***** IS LESS THAN RDIS DEGREES	DENCLUS	4
COMMON/B2/ NDENSE,KPCUT,IFLAG(500)	DENCLUS	5
COMMON/B3/ RDIS,ISPHER,LANS	DENCLUS	6
NDENSE1=NDENSE-1	DENCLUS	7
DO 6 K=1,NDENSE1	DENCLUS	8
K1=K+1	DENCLUS	9
DO 6 J=K1,NDENSE	DENCLUS	10
FD=DIST2(K,J)	DENCLUS	11
301 IF(FD .GE. RDIS .OR. IFLAG(K) .EQ. IFLAG(J)) GO TO 6	DENCLUS	12
CALL CHANGE(IFLAG(J),IFLAG(K))	DENCLUS	13
DO 7 NN=1,NDENSE	DENCLUS	14
IF(IFLAG(NN) .EQ. IFLAG(J)) IFLAG(NN)=IFLAG(K)	DENCLUS	15
7 CONTINUE	DENCLUS	16
6 CONTINUE	DENCLUS	17
RETURN	DENCLUS	18
END	DENCLUS	19
SUBROUTINE PLTPT(A,D,N)	PLTPT	1
C***** PLOT THE ARRAY (A(I),D(I),I=1,N) (POLAR EQUAL AREA	PLTPT	2
C***** PROJECTION	PLTPT	3
COMMON/B5/ LPAGE(130,78)	PLTPT	4
COMMON/B26/ ICUT	PLTPT	5
DIMENSION A(N),D(N)	PLTPT	6
DATA IPLUS/1H+ /	PLTPT	7
ICUT=0	PLTPT	8
DO 777 KK=1,N	PLTPT	9
IF(D(KK) - 90.0) 778,778,776	PLTPT	10
776 D180=180.0-D(KK)	PLTPT	11
CALL SPRPAG(IX,IY,D180,A(KK))	PLTPT	12
LPAGE(IX,IY)=1H+ /	PLTPT	13
ICUT=KK	PLTPT	14
777 CONTINUE	PLTPT	15
778 IF(ICUT .EQ. 0) GO TO 783	PLTPT	16
WRITE(6,781)	PLTPT	17
781 FORMAT(1H1,*LOWER HEMISPHERE*//)	PLTPT	18
CALL POLARC	PLTPT	19
783 RETURN	PLTPT	20
ENTRY PLTPT1	PLTPT	21
780 ICUT1=ICUT+1	PLTPT	22
DO 779 KK=ICUT1,N	PLTPT	23
CALL SPRPAG(IX,IY,D(KK),A(KK))	PLTPT	24
779 LPAGE(IX,IY)=1H+ /	PLTPT	25

WRITE(6,782)	PLTPT	26
782 FORMAT(1H1,*UPPER HEMISPHERE*//)	PLTPT	27
CALL POLARC	PLTPT	28
RETURN	PLTPT	29
END	PLTPT	30
SUBROUTINE INIT(RADIUS)	INIT	1
C***** INITIALIZE CONSTANTS AND VARIABLES	INIT	2
COMMON/B1/ AZ(500),DIP(500),NOBS	INIT	3
COMMON/B2/ NDENSE,KPCUT,IFLAG(500)	INIT	4
COMMON/B4/ NXMID,NYMID,NX,NY,XCONV,YCONV	INIT	5
COMMON/B7/ B(500)	INIT	6
COMMON/B9/ LPATCH(800),KBAND(800)	INIT	7
COMMON/B10/ POS(800)	INIT	8
COMMON/B11/ IBND(36)	INIT	9
COMMON/B12/ DEGRAD,RADEG	INIT	10
COMMON/B16/ DANG(37)	INIT	11
DATA C90/90.0/	INIT	12
DATA DEGRAD/0.0174532925/,RADEG/57.2957795131/	INIT	13
DATA DANG/180.0,175.9,171.9,164.8,160.1,154.2,149.3,	INIT	14
1 144.1,139.5,134.0,129.1,124.1,119.3,114.5,109.9,105.1,	INIT	15
2 100.4,95.2,90.0,84.8,79.6,74.9,70.1,65.5,60.7,55.9,	INIT	16
3 50.9,46.0,40.5,35.9,30.7,25.8,19.9,15.2,8.1,4.1,0.0/,	INIT	17
4 IBND/1,3,10,10,16,16,20,20,26,26,28,28,30,30,32,32,	INIT	18
5 36,36,36,36,32,32,30,30,28,28,26,26,20,20,16,16,	INIT	19
6 10,10,3,1/,	INIT	20
7 KBAND/1,3*2,10*3,10*4,16*5,16*6,20*7,20*8,26*9,26*10,	INIT	21
8 28*11,28*12,30*13,30*14,32*15,32*16,36*17,36*18,36*19,	INIT	22
9 36*20,32*21,32*22,30*23,30*24,28*25,28*26,26*27,26*28,	INIT	23
1 20*29,20*30,16*31,16*32,10*33,10*34,3*35,1*36/	INIT	24
INTEGER B	INIT	25
M=0	INIT	26
DO 3 J=1,36	INIT	27
IBJ=IBND(J)	INIT	28
DO 4 K=1,IBJ	INIT	29
M=M+1	INIT	30
POS(M)=K	INIT	31
4 CONTINUE	INIT	32
3 CONTINUE	INIT	33
ENTRY INITI	INIT	34
DO 1 J=1,NOBS	INIT	35
1 B(J)=0	INIT	36
DO 2 J=1,500	INIT	37
2 IFLAG(J)=J	INIT	38
RETURN	INIT	39
ENTRY INITR	INIT	40
IF(RADIUS .LE. 0.0) RETURN	INIT	41
XPINCH=10.0	INIT	42
YPINCH=6.0	INIT	43
NT=RADIUS*XPINCH+0.5	INIT	44
NX=2*NT+1	INIT	45
NT=RADIUS*YPINCH+0.5	INIT	46
NY=2*NT+1	INIT	47
NX1=NX-1	INIT	48
NY1=NY-1	INIT	49
NYMID=NY/2+1	INIT	50
NXMID=NX/2+1	INIT	51
NXMID1=NXMID-1	INIT	52
NYMID1=NYMID-1	INIT	53
XCON=90/NXMID1	INIT	54

XCONV=1.0/XCON	INIT	55
YCON=Q9C/NYMID1	INIT	56
YCONV=1.0/YCON	INIT	57
RETURN	INIT	58
END	INIT	59
SUBROUTINE SUMCOS	SUMCOS	1
C***** COMPUTE (X,Y,Z) COORDINATES OF RESULTANT OF CLUSTER CU1,CU2	SUMCOS	2
COMMON/B13/ KOU	SUMCOS	3
COMMON/B15/ SLL(500),SMM(500),SNN(500)	SUMCOS	4
COMMON/B19/ SX,SY,SZ	SUMCOS	5
SX=SY=SZ=0.0	SUMCOS	6
DO 1 K=1,KOU	SUMCOS	7
SX=SX+SLL(K)	SUMCOS	8
SY=SY+SMM(K)	SUMCOS	9
SZ=SZ+SNN(K)	SUMCOS	10
1 CONTINUE	SUMCOS	11
RETURN	SUMCOS	12
END	SUMCOS	13
SUBROUTINE SORT(X,Y,N)	SORT	1
C SORT THE N ELEMENTS OF X AND Y IN DESCENDING ORDER OF X	SORT	2
DIMENSION X(N),Y(N),LT(20),UT(20)	SORT	3
J=N	SORT	4
I=1	SORT	5
M=1	SORT	6
5 IF(J-I-1)85,85,10	SORT	7
10 IP=(I+J)/2	SORT	8
T=X(IP)	SORT	9
X(IP)=X(I)	SORT	10
YT=Y(IP)	SORT	11
Y(IP)=Y(I)	SORT	12
IQ=J	SORT	13
K=I+1	SORT	14
15 IF(K-IQ) 25,25,65	SORT	15
25 IF(X(K)-T)40,55,55	SORT	16
40 IF(X(IQ)-T)60,60,50	SORT	17
50 P=X(K)	SORT	18
X(K)=X(IQ)	SORT	19
X(IQ)=P	SORT	20
YP=Y(K)	SORT	21
Y(K)=Y(IQ)	SORT	22
Y(IQ)=YP	SORT	23
IQ=IQ-1	SORT	24
55 K=K+1	SORT	25
GO TO 15	SORT	26
60 IQ=IQ-1	SORT	27
IF(IQ-K)65,40,40	SORT	28
65 X(I)=X(IQ)	SORT	29
X(IQ)=T	SORT	30
Y(I)=Y(IQ)	SORT	31
Y(IQ)=YT	SORT	32
IF(2*IQ-I-J)75,75,70	SORT	33
70 LT(M)=I	SORT	34
UT(M)=IQ-1	SORT	35
I=IQ+1	SORT	36
GO TO 80	SORT	37
75 LT(M)=IQ+1	SORT	38
UT(M)=J	SORT	39
J=IQ-1	SORT	40
80 M=M+1	SORT	41

```

      GO TO 5
85  IF(I-J)95,110,110
95  IF(X(I)-X(J))105,110,110
105 P=X(I)
     X(I)=X(J)
     X(J)=P
     YP=Y(I)
     Y(I)=Y(J)
     Y(J)=YP
110 IF(M-1)120,120,115
115 M=M-1
     I=LT(M)
     J=UT(M)
     GO TO 5
120 RETURN
     END
     FUNCTION DIST3(I,J)
C***** DIST3 = DISTANCE FROM POINT NUMBER I TO THE NEGATIVE OF POINT
C***** NUMBER J.
     COMMON/B8/ SL(500),SM(500),SN(500)
     DIST3=(SL(I)+SL(J))**2+(SM(I)+SM(J))**2+(SN(I)+SN(J))**2
     RETURN
     END
     SUBROUTINE XLEVEL(KK1)
     COMMON/B1/ A(500),D(500),N
     COMMON/B9/ LPATCH(800),KBAND(800)
     COMMON/B20/ RLEVEL(800)
     FN=FLOAT(N)
     RLEVEL(KK1)=FLCAT(LPATCH(KK1))/FN
     KK2=KK1+1
     DO 1 J=KK2,800
     JM1=J-1
     RLEVEL(J)=FLOAT(LPATCH(J)-LPATCH(JM1))/FN
1  CONTINUE
     RETURN
     END

```

```

SORT      42
SORT      43
SORT      44
SORT      45
SORT      46
SORT      47
SORT      48
SORT      49
SORT      50
SORT      51
SORT      52
SORT      53
SORT      54
SORT      55
SORT      56
SORT      57
DIST3     1
DIST3     2
DIST3     3
DIST3     4
DIST3     5
DIST3     6
DIST3     7
XLEVEL    1
XLEVEL    2
XLEVEL    3
XLEVEL    4
XLEVEL    5
XLEVEL    6
XLEVEL    7
XLEVEL    8
XLEVEL    9
XLEVEL    10
XLEVEL    11
XLEVEL    12
XLEVEL    13

```

EXAMPLE OUTPUT

AXIAL DATA CONSISTING OF 6 HEMISPHERICALLY NORMAL CLUSTERS

NOBS = 144

LANS = 0

ISPHER = 0

RDIS = 12.5

RADIUS OF POINT PLOT = 4.0

RADIUS OF DENSITY PLOT = 6.0

AZIMUTH OF THE DIP AND DIP OF THE DATA POINTS

360	60	0	61	1	57	4	57	351	58	356	69
349	65	9	71	347	49	0	76	20	55	348	75
357	79	337	60	8	41	22	66	24	67	339	42
6	36	352	84	329	64	2	89	335	37	32	44
72	60	72	61	74	57	77	63	66	59	64	55
80	52	69	75	56	53	53	51	80	77	67	79
77	41	74	40	87	76	71	81	50	69	49	47
98	51	85	80	102	63	44	70	101	68	47	37
144	57	146	63	145	56	140	65	136	56	134	68
157	67	143	46	158	69	128	68	129	48	161	68
165	53	143	41	148	40	129	75	142	39	131	80
172	58	149	85	137	34	113	68	178	61	161	85
217	59	218	59	210	64	215	54	222	68	205	53
223	71	204	68	199	52	229	70	232	50	197	55
226	76	239	58	215	80	193	66	220	36	241	69
212	84	187	56	247	54	186	51	193	78	236	83
288	59	288	61	288	59	287	58	291	69	278	66
301	54	297	71	299	71	286	76	272	50	277	46
298	44	306	68	269	69	310	49	310	48	301	78
262	58	269	78	269	38	278	85	321	59	300	87
168	3	261	3	168	4	336	5	302	8	42	9
230	10	14	14	19	15	163	15	248	15	201	17
324	19	131	19	26	20	356	21	23	21	297	21
257	22	113	24	187	28	86	28	94	29	341	30

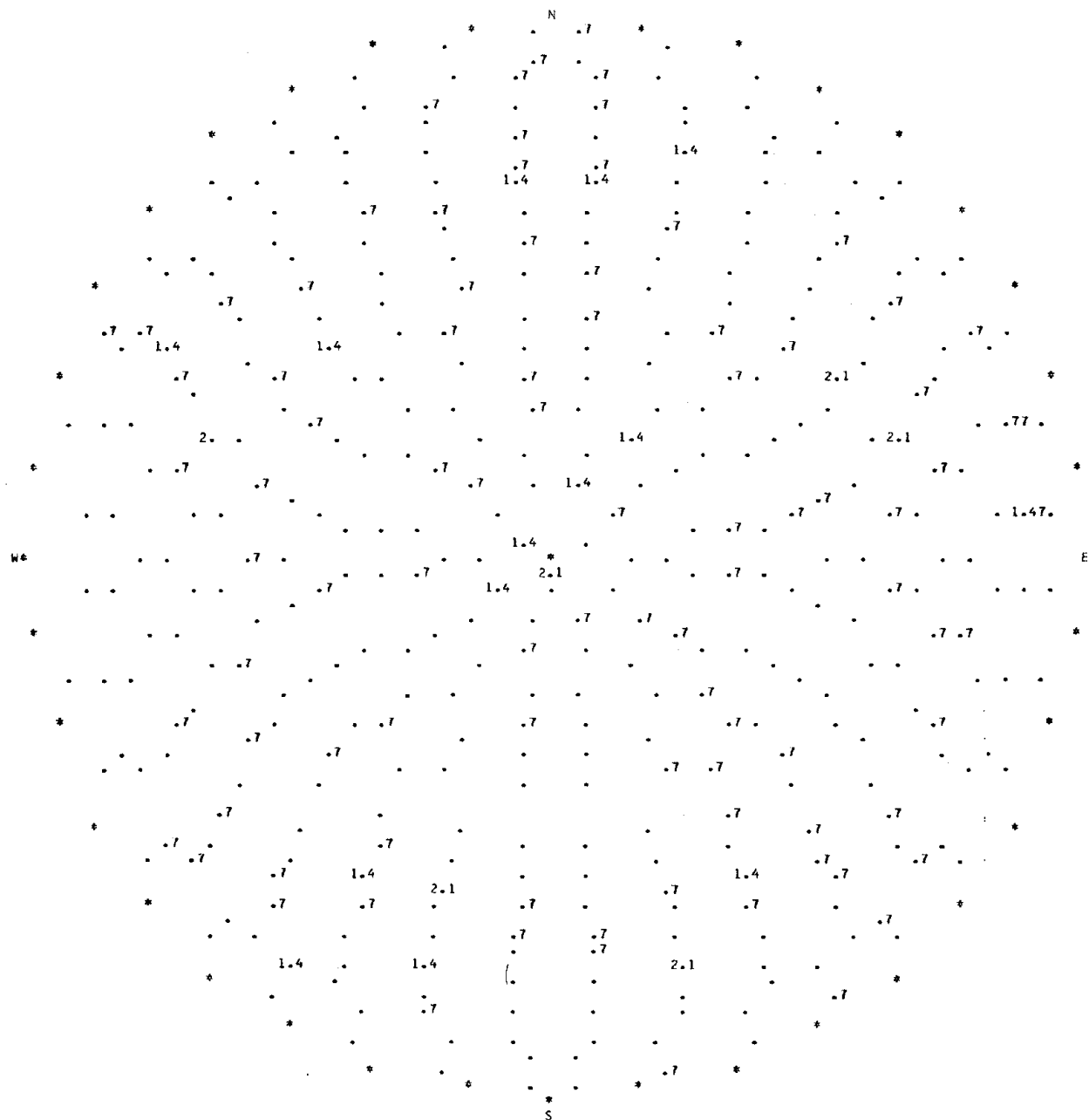
FOR RDIS = 12.50 PERCENTAGE OF SURFACE AREA IS 2.37

A POINT X IS DENSE IF THERE ARE 7 OBSERVATIONS

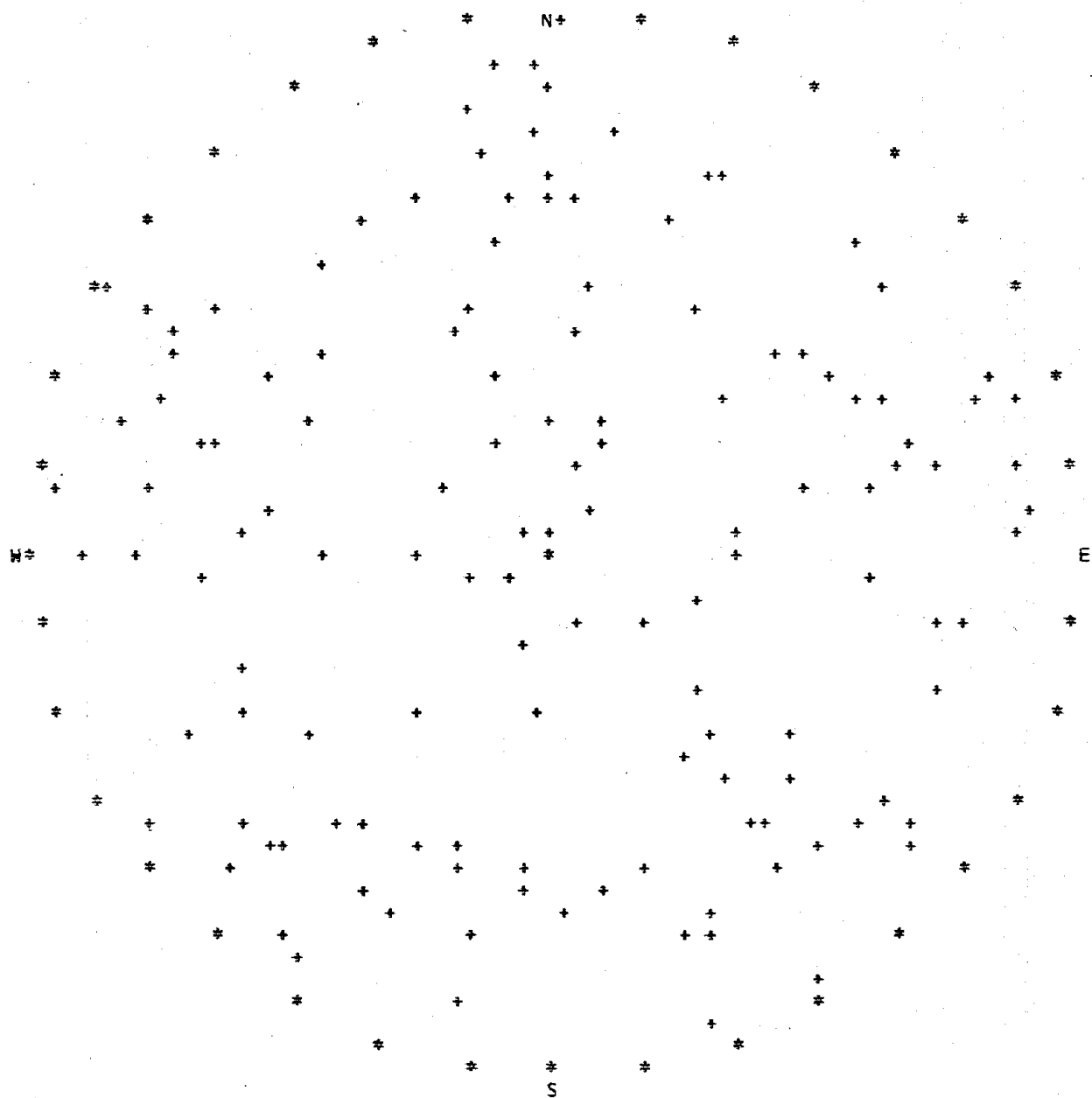
WHOSE EUCLIDEAN DISTANCE FROM X IS LESS THAN 4.74E-02.

DENSITY PLOT - LOWER AND UPPER HEMISPHERES

UPPER HEMISPHERE

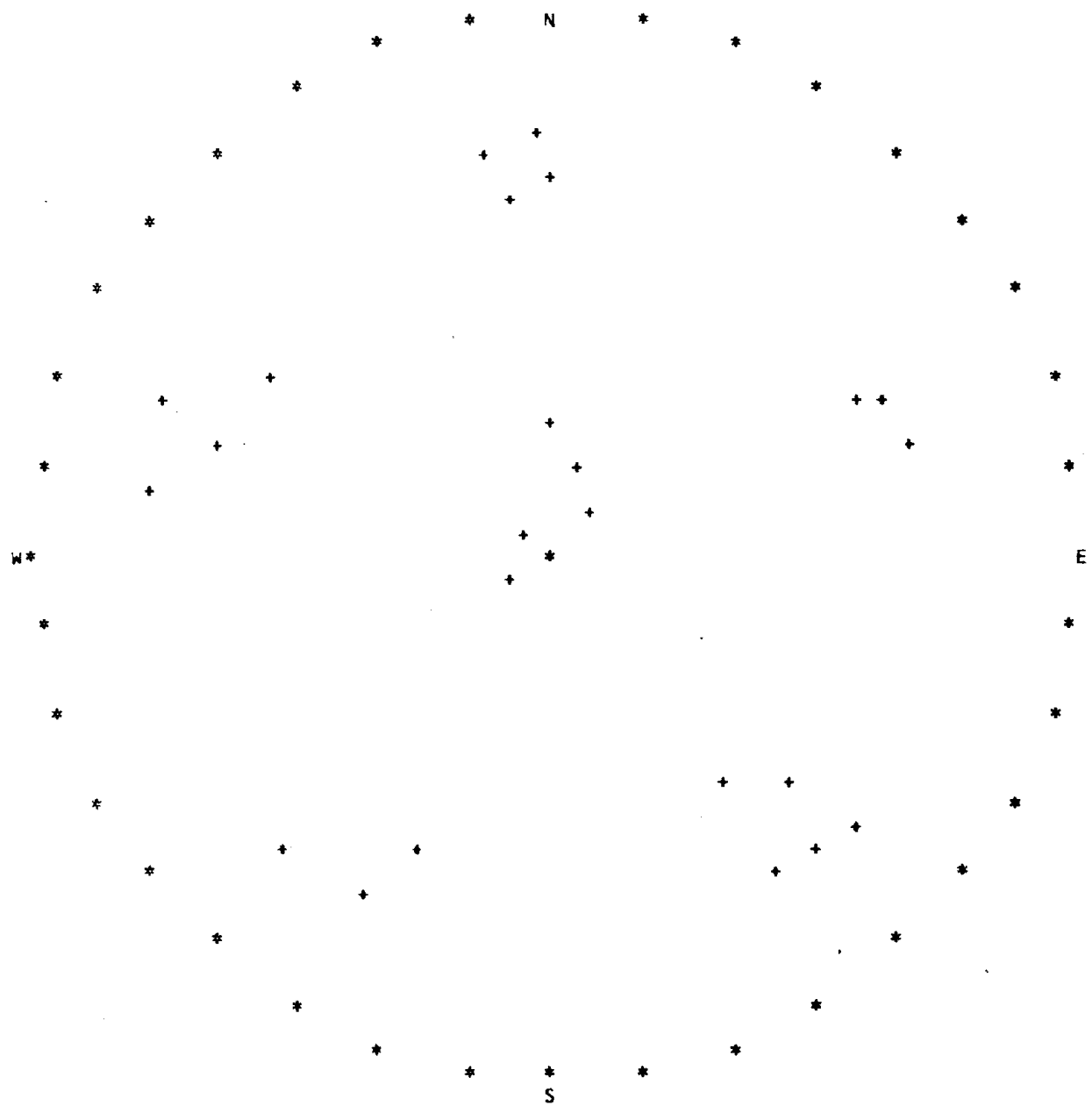


UPPER HEMISPHERE



DATA PLOT(POLAR EQUAL AREA PROJECTION).
THERE ARE 144 POINTS IN THE SAMPLE.

UPPER HEMISPHERE



THERE ARE 25 DENSE POINTS.

OUTPUT OF CLUSTERS, CLUSTER MEANS

CLUSTER NUMBER 1

NUM	AZIMUTH	INCLINATION
1	149.00	85.00
2	161.00	85.00
3	131.00	80.00
4	129.00	75.00
5	113.00	68.00
6	128.00	68.00
7	134.00	68.00
8	157.00	67.00
9	158.00	69.00
10	161.00	68.00
11	140.00	65.00
12	146.00	63.00
13	136.00	56.00
14	144.00	57.00
15	145.00	56.00
16	172.00	58.00
17	165.00	53.00
18	129.00	48.00
19	143.00	46.00
20	143.00	41.00
21	142.00	39.00
22	148.00	40.00
23	137.00	34.00

MEAN

AZIMUTH 144.02 DEG

INCLINATION 59.66 DEG

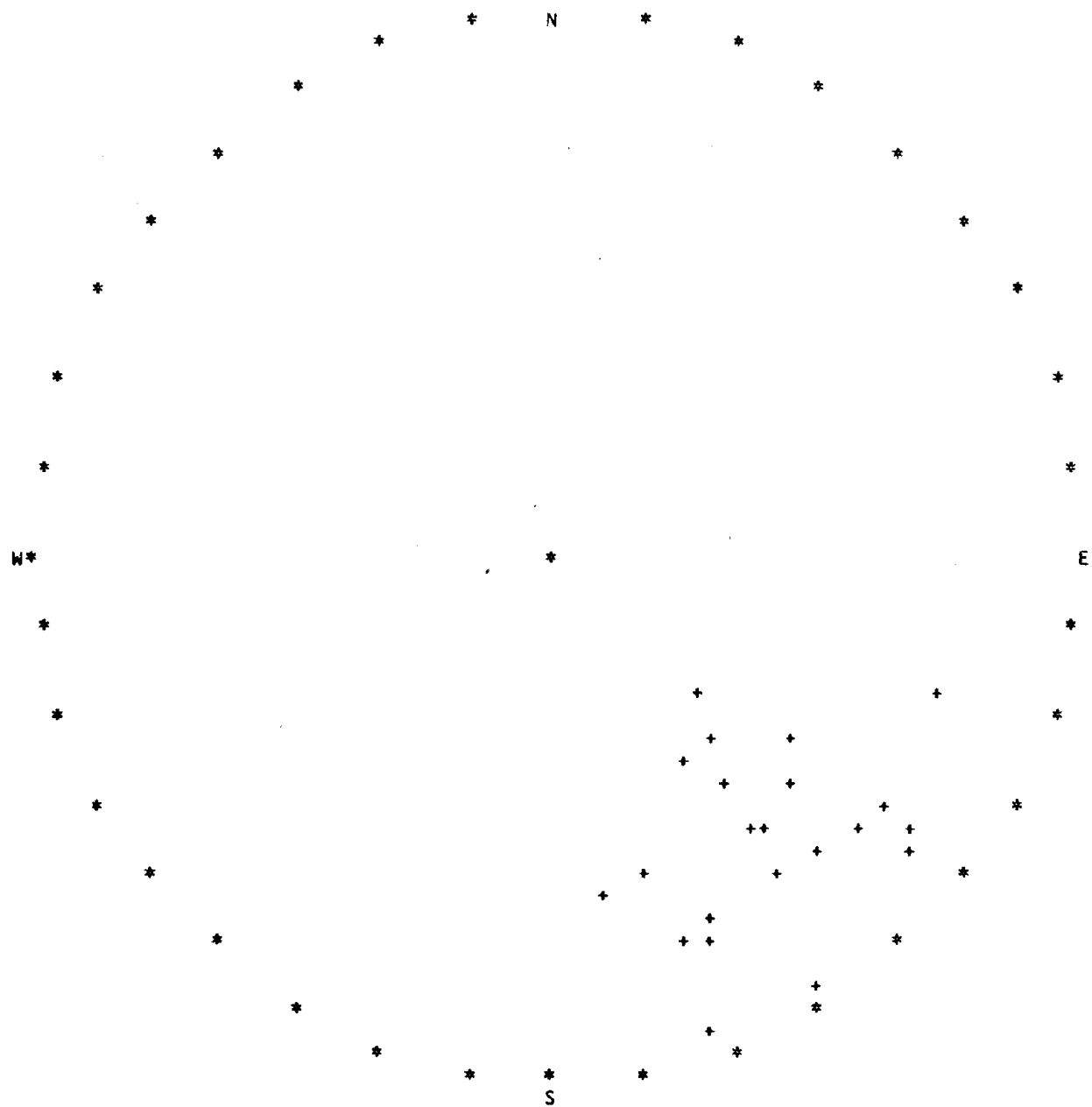
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

21.80881 -15.23083 11.05826 11.01640

CENTER OF GRAVITY - (X,Y,Z) COORDINATES

-.6622 .4808 .4790

UPPER HEMISPHERE



CLUSTER NO. 1 CONTAINS 23 POINTS.
FOR THIS ANALYSIS, RCIS = 12.50

CLUSTER NUMBER 2

NUM	AZIMUTH	INCLINATION
1	212.00	84.00
2	215.00	80.00
3	236.00	83.00
4	193.00	78.00
5	226.00	76.00
6	223.00	71.00
7	193.00	66.00
8	204.00	68.00
9	222.00	68.00
10	229.00	70.00
11	241.00	69.00
12	178.00	61.00
13	210.00	64.00
14	187.00	56.00
15	217.00	59.00
16	218.00	59.00
17	239.00	58.00
18	186.00	51.00
19	197.00	55.00
20	199.00	52.00
21	205.00	53.00
22	215.00	54.00
23	247.00	54.00
24	232.00	50.00
25	220.00	36.00

MEAN

AZIMUTH 213.97 DEG

INCLINATION 61.82 DEG

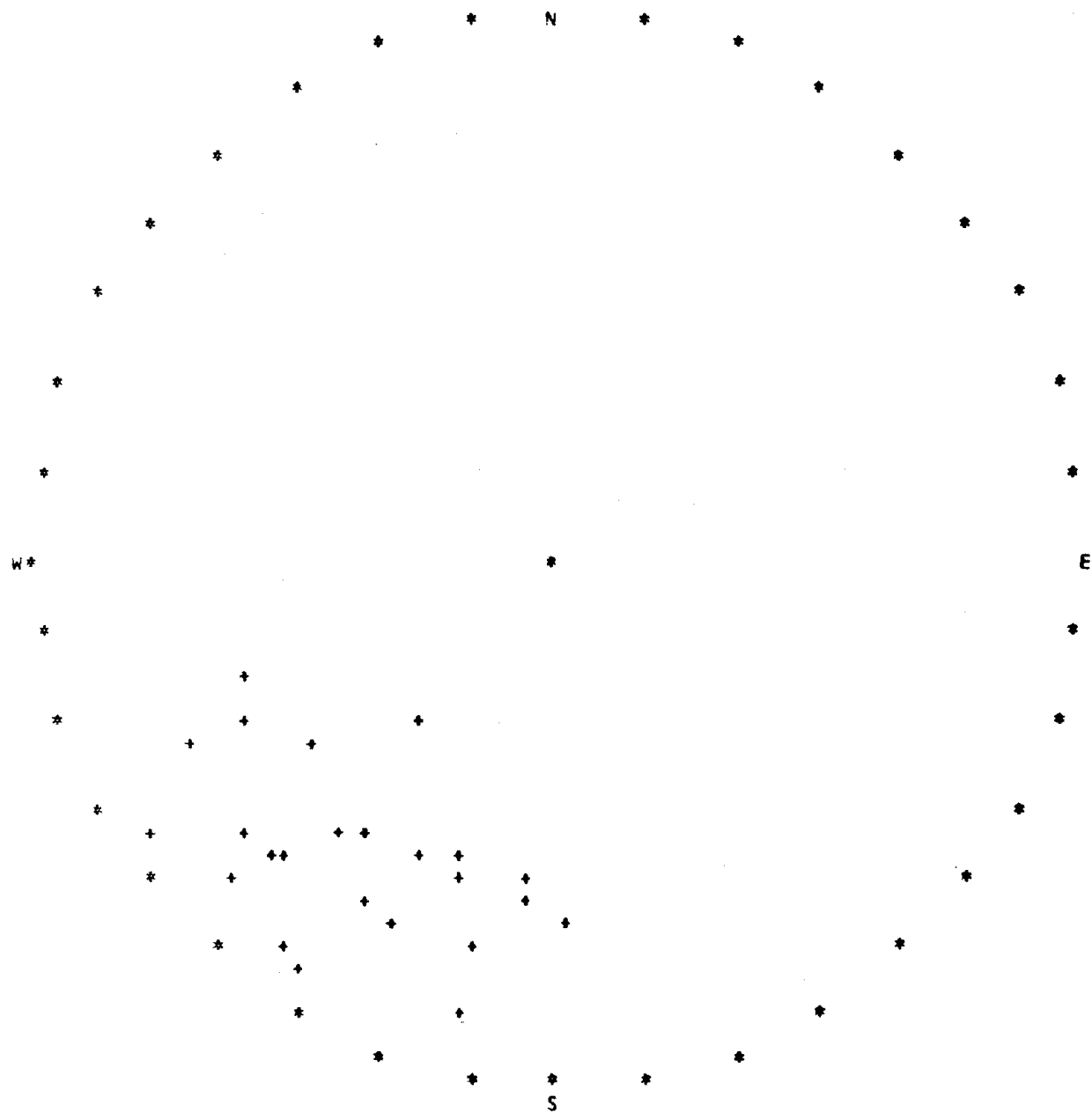
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

23.55255 -17.21700 -11.60176 11.12190

CENTER OF GRAVITY - (X, Y, Z) COORDINATES

-.6887 -.4641 .4449

UPPER HEMISPHERE



CLUSTER NO. 2 CONTAINS 25 POINTS.
FOR THIS ANALYSIS, RLIS = 12.50

CLUSTER NUMBER 3

33

NUM	AZIMUTH	INCLINATION
1	278.00	85.00
2	300.00	87.00
3	269.00	78.00
4	286.00	76.00
5	301.00	78.00
6	297.00	71.00
7	299.00	71.00
8	269.00	69.00
9	278.00	66.00
10	291.00	69.00
11	306.00	68.00
12	288.00	61.00
13	262.00	58.00
14	287.00	58.00
15	288.00	59.00
16	288.00	59.00
17	321.00	59.00
18	301.00	54.00
19	272.00	50.00
20	277.00	46.00
21	310.00	49.00
22	310.00	48.00
23	298.00	44.00
24	269.00	38.00

MEAN

AZIMUTH 289.42 DEG

INCLINATION 61.73 DEG

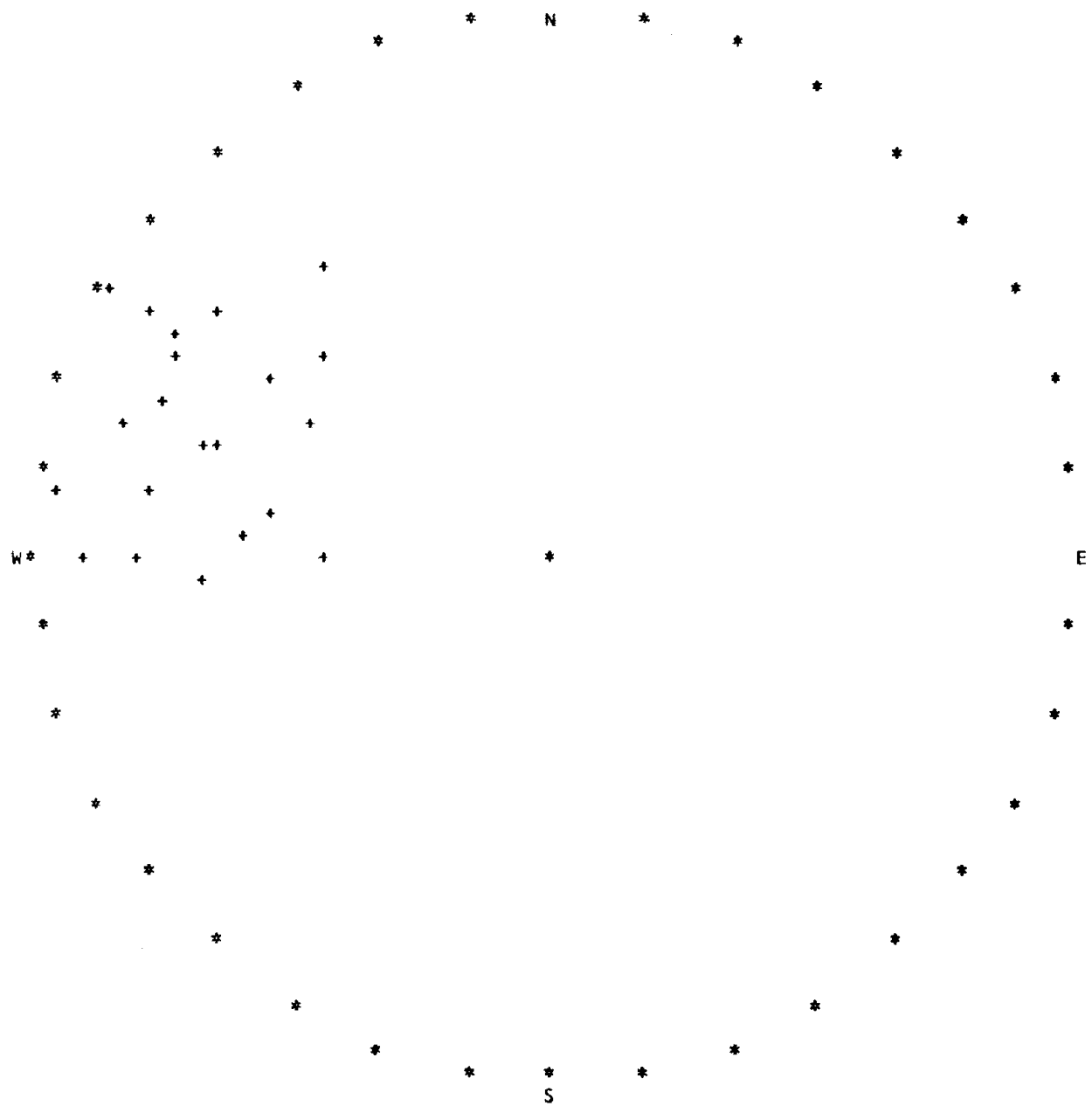
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

22.79199 6.67552 -18.93151 10.79399

CENTER OF GRAVITY - (X,Y,Z) COORDINATES

.2781 -.7888 .4497

UPPER HEMISPHERE



CLUSTER NO. 3 CONTAINS 24 POINTS.
FOR THIS ANALYSIS, RDIS = 12.50

CLUSTER NUMBER 4

NUM	AZIMUTH	INCLINATION
1	2.00	89.00
2	352.00	84.00
3	0.00	76.00
4	348.00	75.00
5	357.00	79.00
6	9.00	71.00
7	22.00	66.00
8	24.00	67.00
9	356.00	69.00
10	0.00	61.00
11	329.00	64.00
12	349.00	65.00
13	1.00	57.00
14	4.00	57.00
15	337.00	60.00
16	351.00	58.00
17	360.00	60.00
18	20.00	55.00
19	347.00	49.00
20	339.00	42.00

MEAN

AZIMUTH 357.61 DEG

INCLINATION 64.54 DEG

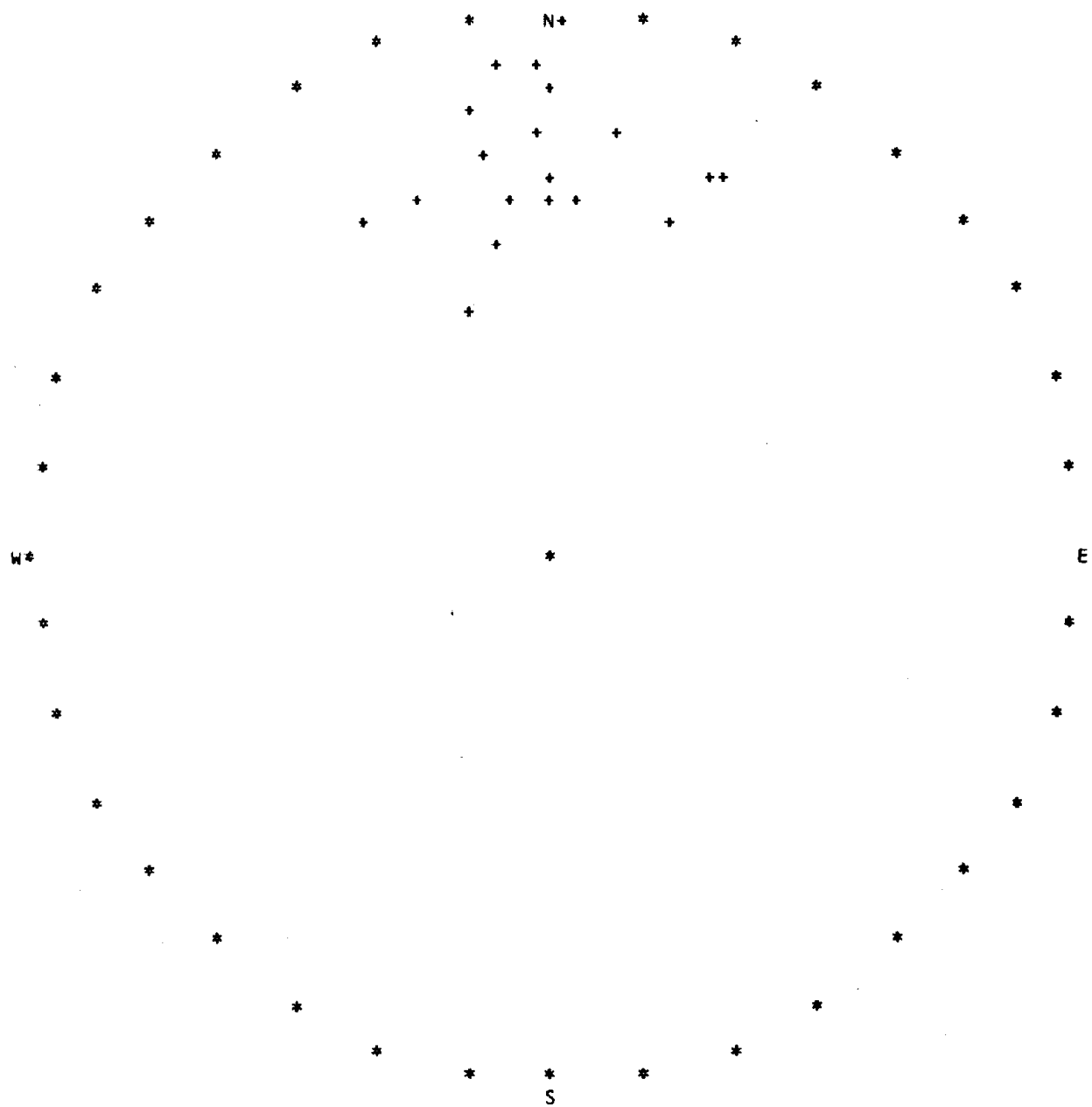
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

19.14823 17.27309 -.71946 8.23271

CENTER OF GRAVITY - (X,Y,Z) COORDINATES

.8637 -.0360 .4116

UPPER HEMISPHERE



CLUSTER NO. 4 CONTAINS 20 POINTS.
FOR THIS ANALYSIS, RDIS = 12.50

CLUSTER NUMBER 5

NUM	AZIMUTH	INCLINATION
1	71.00	81.00
2	85.00	80.00
3	67.00	79.00
4	69.00	75.00
5	80.00	77.00
6	87.00	76.00
7	44.00	70.00
8	50.00	69.00
9	101.00	68.00
10	72.00	61.00
11	77.00	63.00
12	102.00	63.00
13	66.00	59.00
14	72.00	60.00
15	74.00	57.00
16	53.00	51.00
17	56.00	53.00
18	64.00	55.00
19	80.00	52.00
20	98.00	51.00
21	49.00	47.00
22	32.00	44.00
23	77.00	41.00
24	47.00	37.00
25	74.00	40.00

MEAN

AZIMUTH 70.68 DEG

INCLINATION 59.24 DEG

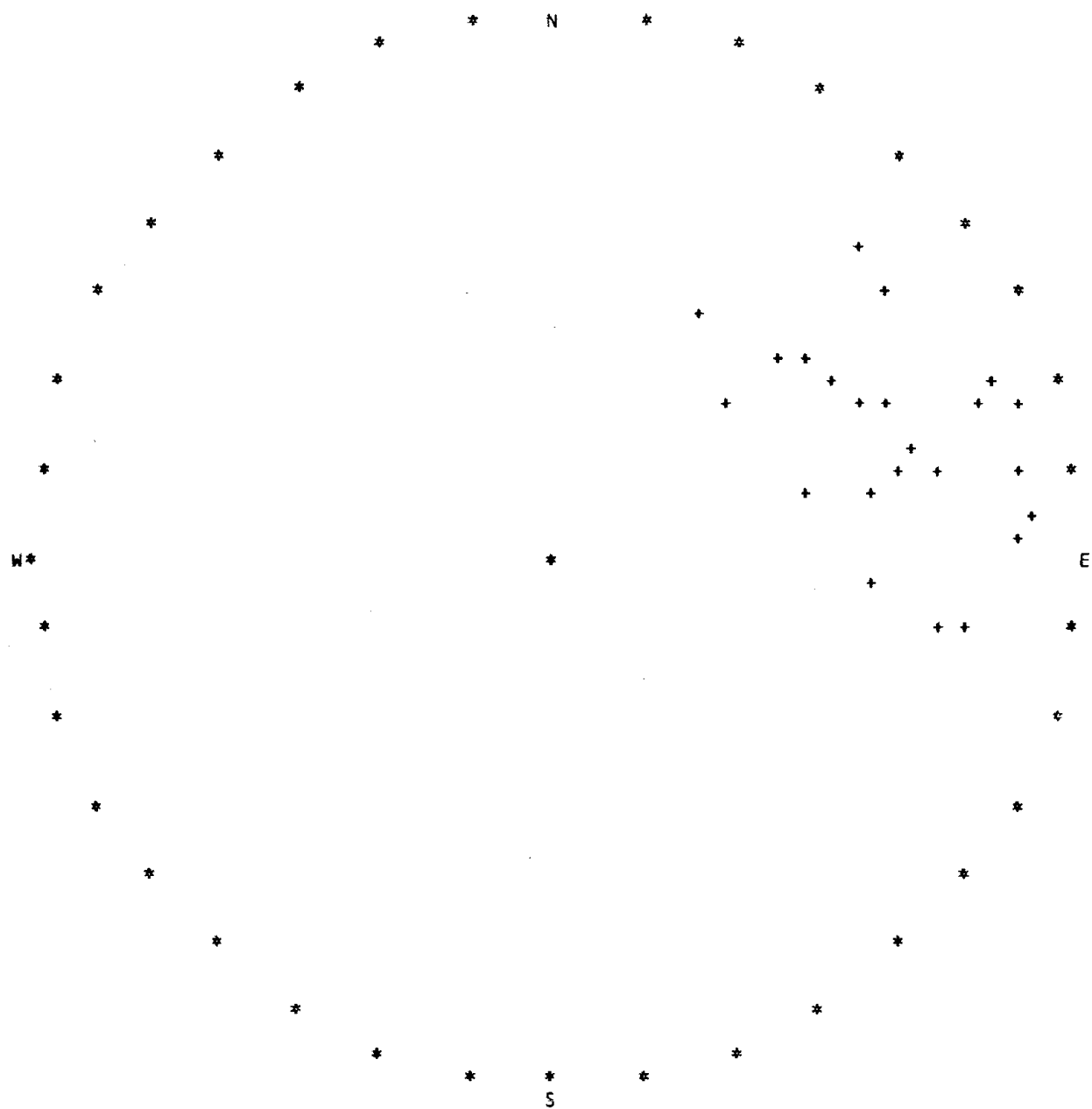
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

23.54675 6.69527 19.09328 12.04447

CENTER OF GRAVITY - (X,Y,Z) COORDINATES

.2678 .7637 .4818

UPPER HEMISPHERE



CLUSTER NO. 5 CONTAINS 25 POINTS.
FOR THIS ANALYSIS, RDIS = 12.50

CLUSTER NUMBER 6

NUM	AZIMUTH	INCLINATION
1	8.00	41.00
2	6.00	36.00
3	335.00	37.00
4	86.00	28.00
5	94.00	29.00
6	187.00	28.00
7	341.00	30.00
8	23.00	21.00
9	26.00	20.00
10	113.00	24.00
11	257.00	22.00
12	297.00	21.00
13	356.00	21.00
14	131.00	19.00
15	201.00	17.00
16	324.00	19.00
17	14.00	14.00
18	19.00	15.00
19	42.00	9.00
20	163.00	15.00
21	230.00	10.00
22	248.00	15.00
23	302.00	8.00
24	336.00	5.00
25	168.00	4.00
26	168.00	3.00
27	261.00	3.00

MEAN

AZIMUTH 6.59 DEG

INCLINATION 6.04 DEG

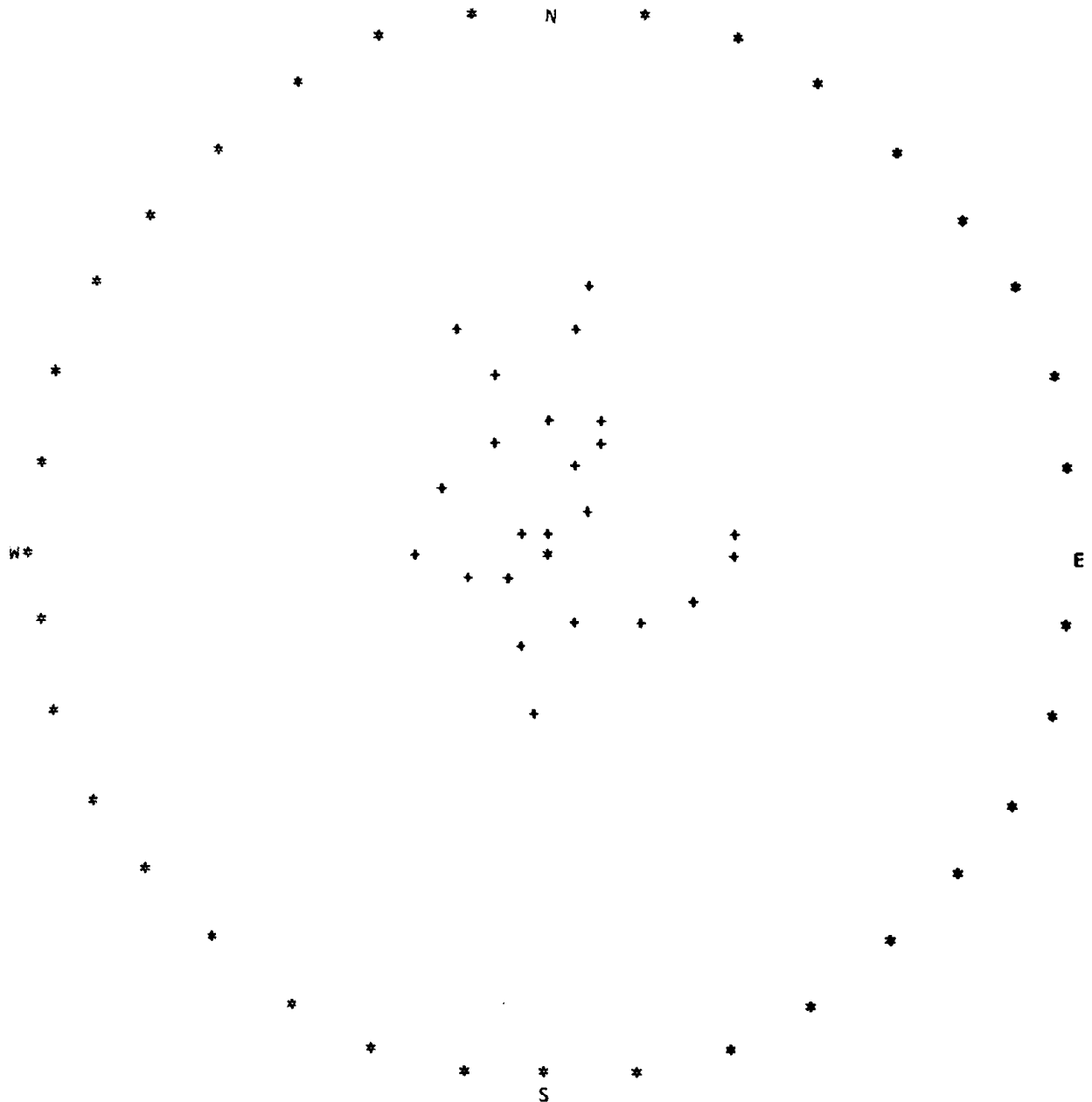
RESULTANT AND ITS COMPONENTS - R, Sx, Sy, Sz.

25.25966 2.64190 .30534 25.11926

CENTER OF GRAVITY - (X,Y,Z) COORDINATES

.0978 .0113 .9303

UPPER HEMISPHERE



CLUSTER NO. 6 CONTAINS 27 POINTS.
FOR THIS ANALYSIS, RMS = 12.50

OBJECTIVE FUNCTION = 37.301

TIME REQUIRED TO ANALYZE 144 DATA POINTS 8.584 SECONDS

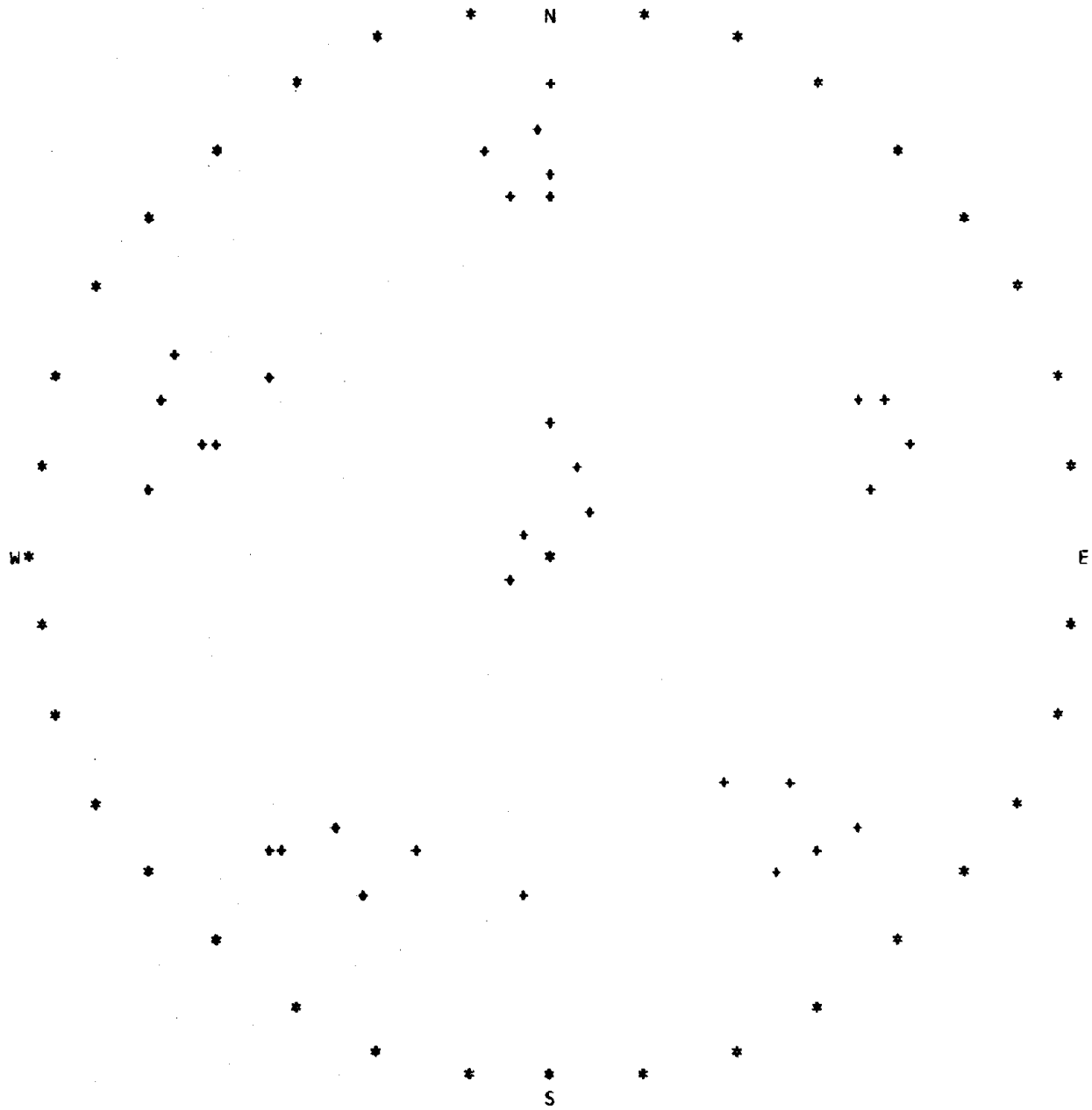
FOR NEXT ANALYSIS OF SAMPLE

LANS = 0

RDIS = 13.5

FOR RDIS = 13.50 PERCENTAGE OF SURFACE AREA IS 2.76
A POINT X IS DENSE IF THERE ARE 7 OBSERVATIONS
WHOSE EUCLIDEAN DISTANCE FROM X IS LESS THAN $5.53E-02$.

UPPER HEMISPHERE



THERE ARE 33 DENSE POINTS.

OUTPUT OF CLUSTERS, CLUSTER MEANS

CLUSTER NUMBER 1

NUM	AZIMUTH	INCLINATION
1	2.00	89.00
2	352.00	84.00
3	0.00	76.00
4	348.00	75.00
5	357.00	79.00
6	9.00	71.00
7	22.00	66.00
8	24.00	67.00
9	356.00	69.00
10	0.00	61.00
11	329.00	64.00
12	349.00	65.00
13	1.00	57.00
14	4.00	57.00
15	337.00	60.00
16	351.00	58.00
17	360.00	60.00
18	20.00	55.00
19	347.00	49.00
20	8.00	41.00
21	339.00	42.00

MEAN

AZIMUTH 357.99 DEG

INCLINATION 63.38 DEG

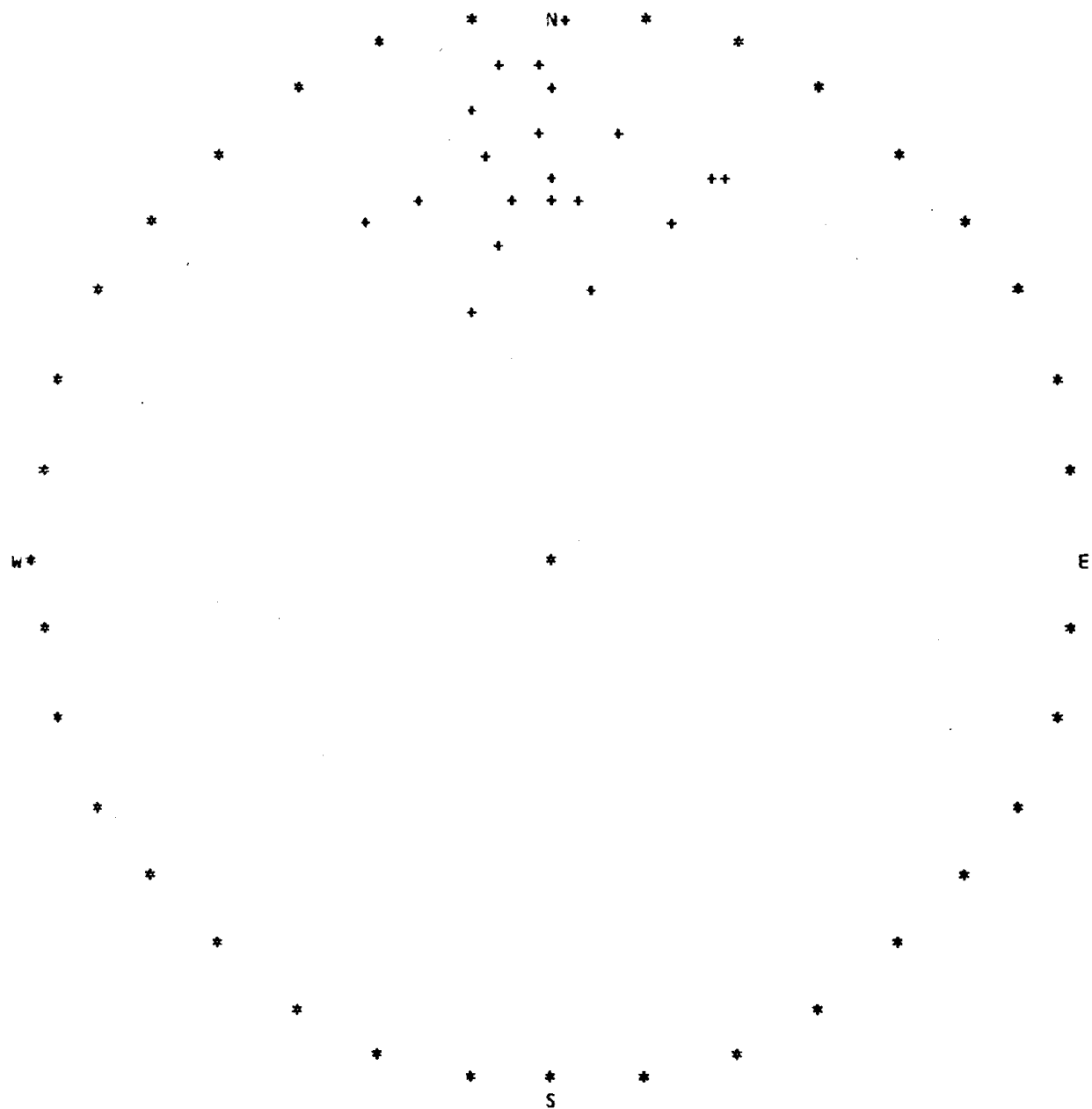
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

20.05976	17.92276	-.62815	8.98742
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CENTER OF GRAVITY - (X,Y,Z) COORDINATES

.8535	-.0299	.4280
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UPPER HEMISPHERE



CLUSTER NO. 1 CONTAINS 21 POINTS.
FOR THIS ANALYSIS, RCIS = 13.50

CLUSTER NUMBER 2

NUM	AZIMUTH	INCLINATION
1	212.00	84.00
2	215.00	80.00
3	236.00	83.00
4	193.00	78.00
5	226.00	76.00
6	223.00	71.00
7	204.00	68.00
8	222.00	68.00
9	229.00	70.00
10	241.00	69.00
11	210.00	64.00
12	217.00	59.00
13	218.00	59.00
14	239.00	58.00
15	197.00	55.00
16	199.00	52.00
17	205.00	53.00
18	215.00	54.00
19	247.00	54.00
20	232.00	50.00
21	220.00	36.00

MEAN

AZIMUTH 219.06 DEG

INCLINATION 63.13 DEG

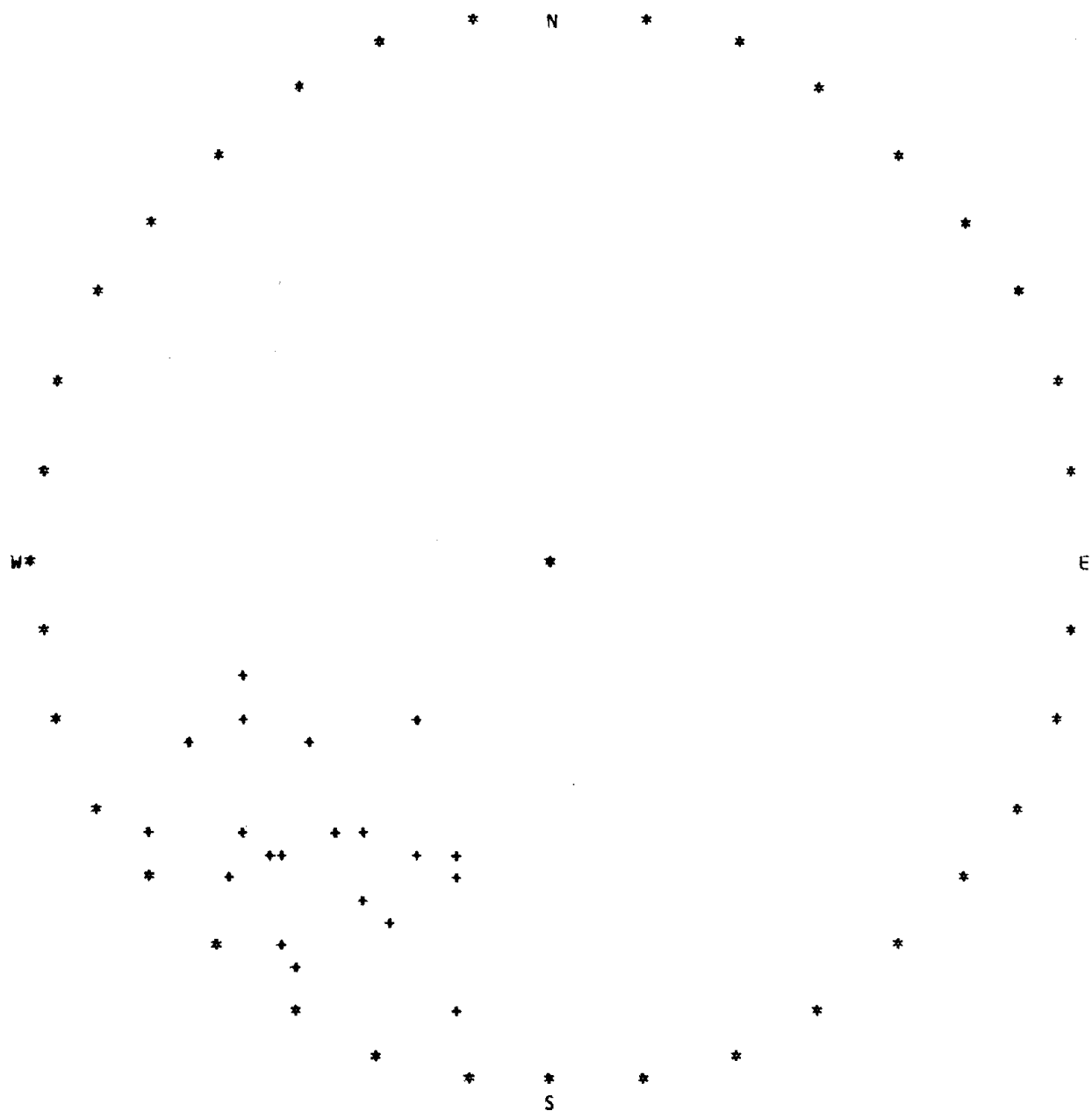
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

20.00528 -13.85704 -11.24451 9.04184

CENTER OF GRAVITY - (X, Y, Z) COORDINATES

-.6599 -.5355 .4306

UPPER HEMISPHERE



CLUSTER NO. 2 CONTAINS 21 POINTS.
FOR THIS ANALYSIS, RDIS = 13.50

CLUSTER NUMBER 3

NUM	AZIMUTH	INCLINATION
1	149.00	85.00
2	161.00	85.00
3	131.00	80.00
4	129.00	75.00
5	113.00	68.00
6	128.00	68.00
7	134.00	68.00
8	157.00	67.00
9	158.00	69.00
10	161.00	68.00
11	140.00	65.00
12	146.00	63.00
13	136.00	56.00
14	144.00	57.00
15	145.00	56.00
16	165.00	53.00
17	129.00	48.00
18	143.00	46.00
19	143.00	41.00
20	142.00	39.00
21	148.00	40.00
22	137.00	34.00

MEAN

AZIMUTH 142.76 DEG

INCLINATION 59.88 DEG

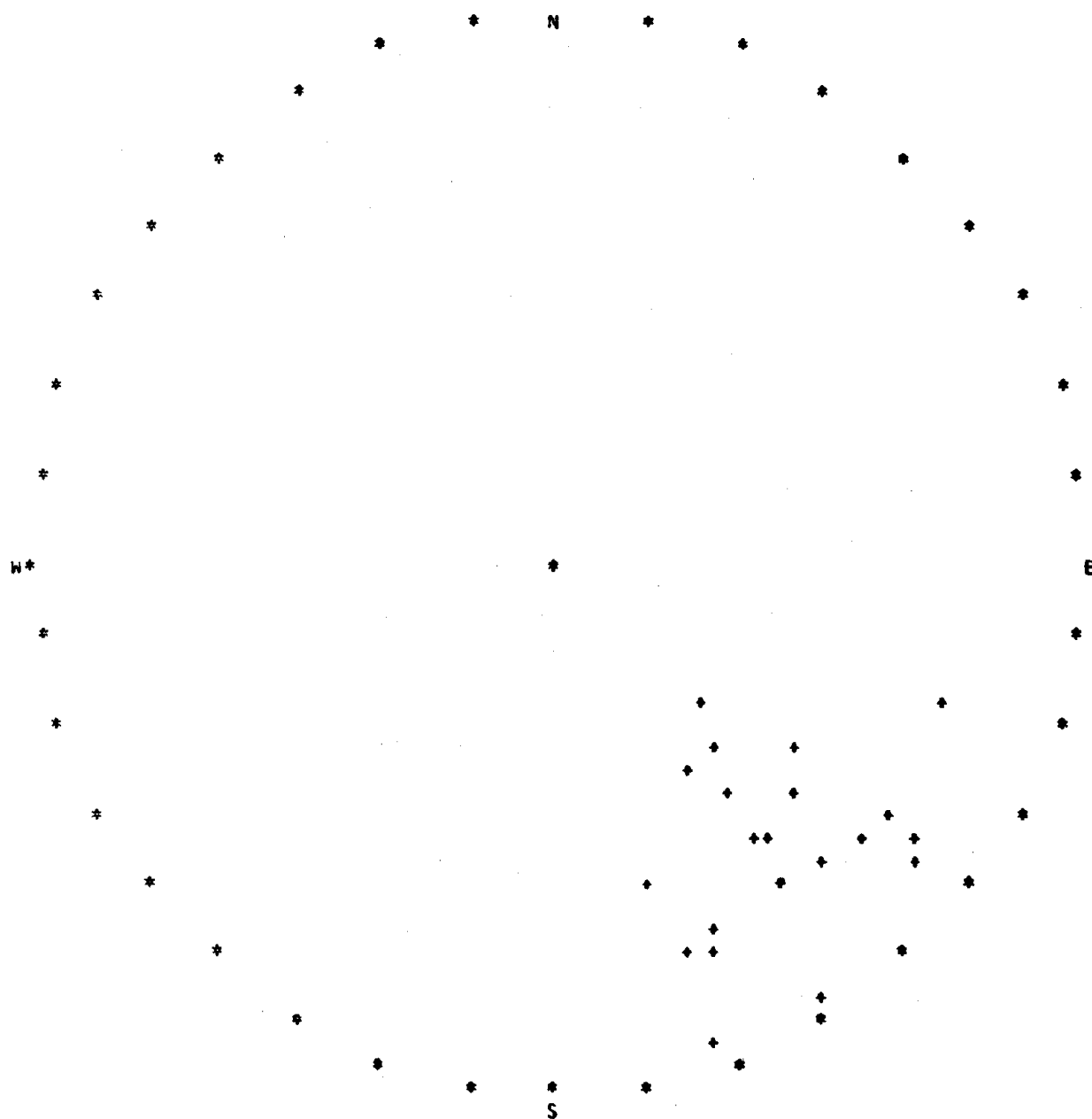
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

20.89873 -14.39103 10.94023 10.48648

CENTER OF GRAVITY - (X, Y, Z) COORDINATES

-.6541 .4973 .4767

UPPER HEMISPHERE



CLUSTER NO. 3 CONTAINS 22 POINTS.
FOR THIS ANALYSIS, ROIS = 13.50

CLUSTER NUMBER 4

NUM	AZIMUTH	INCLINATION
1	278.00	85.00
2	300.00	87.00
3	269.00	78.00
4	286.00	76.00
5	301.00	78.00
6	297.00	71.00
7	299.00	71.00
8	269.00	69.00
9	278.00	66.00
10	291.00	69.00
11	306.00	68.00
12	288.00	61.00
13	262.00	58.00
14	287.00	58.00
15	288.00	59.00
16	288.00	59.00
17	321.00	59.00
18	301.00	54.00
19	272.00	50.00
20	277.00	46.00
21	310.00	49.00
22	310.00	48.00
23	298.00	44.00
24	269.00	38.00

MEAN

AZIMUTH 289.42 DEG

INCLINATION 61.73 DEG

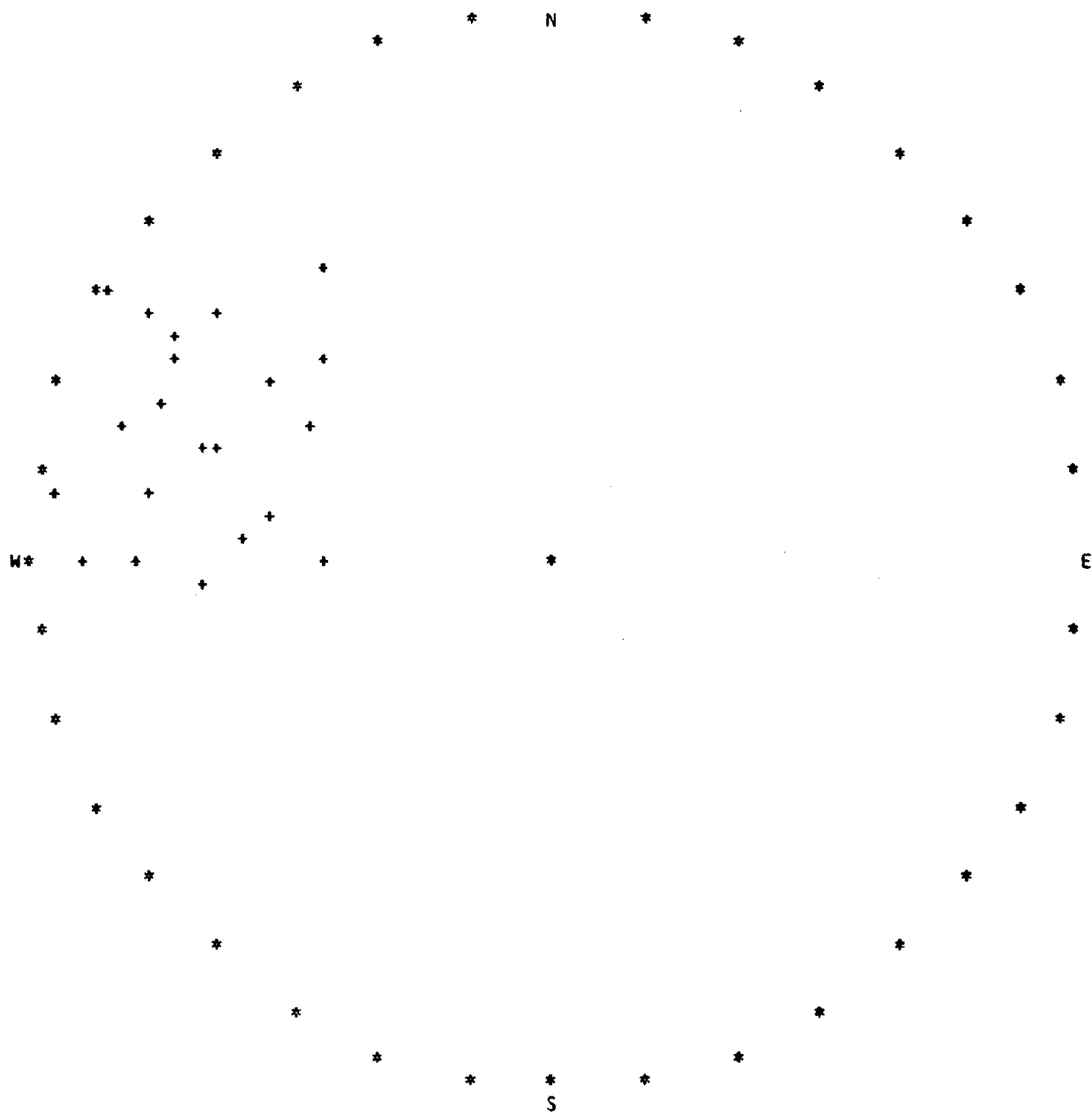
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

22.79199 6.67552 -18.93151 10.79399

CENTER OF GRAVITY - (X,Y,Z) COORDINATES

.2781 -.7888 .4497

UPPER HEMISPHERE



CLUSTER NO. 4 CONTAINS 24 POINTS.
FOR THIS ANALYSIS, RDIS = 13.50

CLUSTER NUMBER 5

NUM	AZIMUTH	INCLINATION
1	71.00	81.00
2	85.00	80.00
3	67.00	79.00
4	69.00	75.00
5	80.00	77.00
6	87.00	76.00
7	44.00	70.00
8	50.00	69.00
9	101.00	68.00
10	72.00	61.00
11	77.00	63.00
12	102.00	63.00
13	66.00	59.00
14	72.00	60.00
15	74.00	57.00
16	53.00	51.00
17	56.00	53.00
18	64.00	55.00
19	80.00	52.00
20	98.00	51.00
21	49.00	47.00
22	32.00	44.00
23	77.00	41.00
24	47.00	37.00
25	74.00	40.00

MEAN

AZIMUTH 70.68 DEG

INCLINATION 59.24 DEG

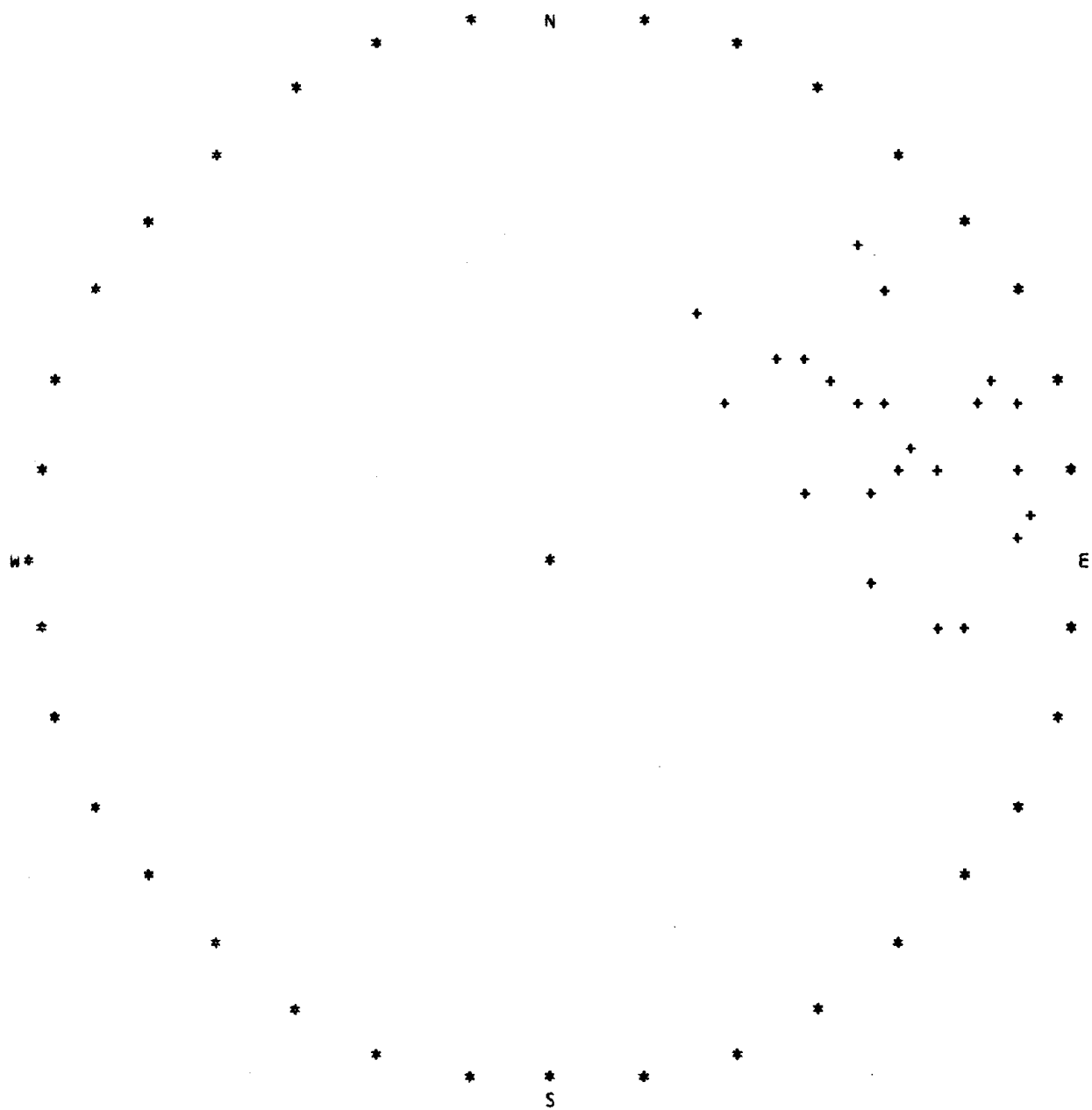
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

23.54675 6.69527 19.09328 12.04447

CENTER OF GRAVITY - (X,Y,Z) COORDINATES

.2678 .7637 .4818

UPPER HEMISPHERE



CLUSTER NO. 5 CONTAINS 25 POINTS.
FOR THIS ANALYSIS, RDIS = 13.50

CLUSTER NUMBER 6

NUM	AZIMUTH	INCLINATION
1	193.00	66.00
2	178.00	61.00
3	172.00	58.00
4	187.00	56.00
5	186.00	51.00

MEAN

AZIMUTH 183.26 DEG

INCLINATION 58.18 DEG

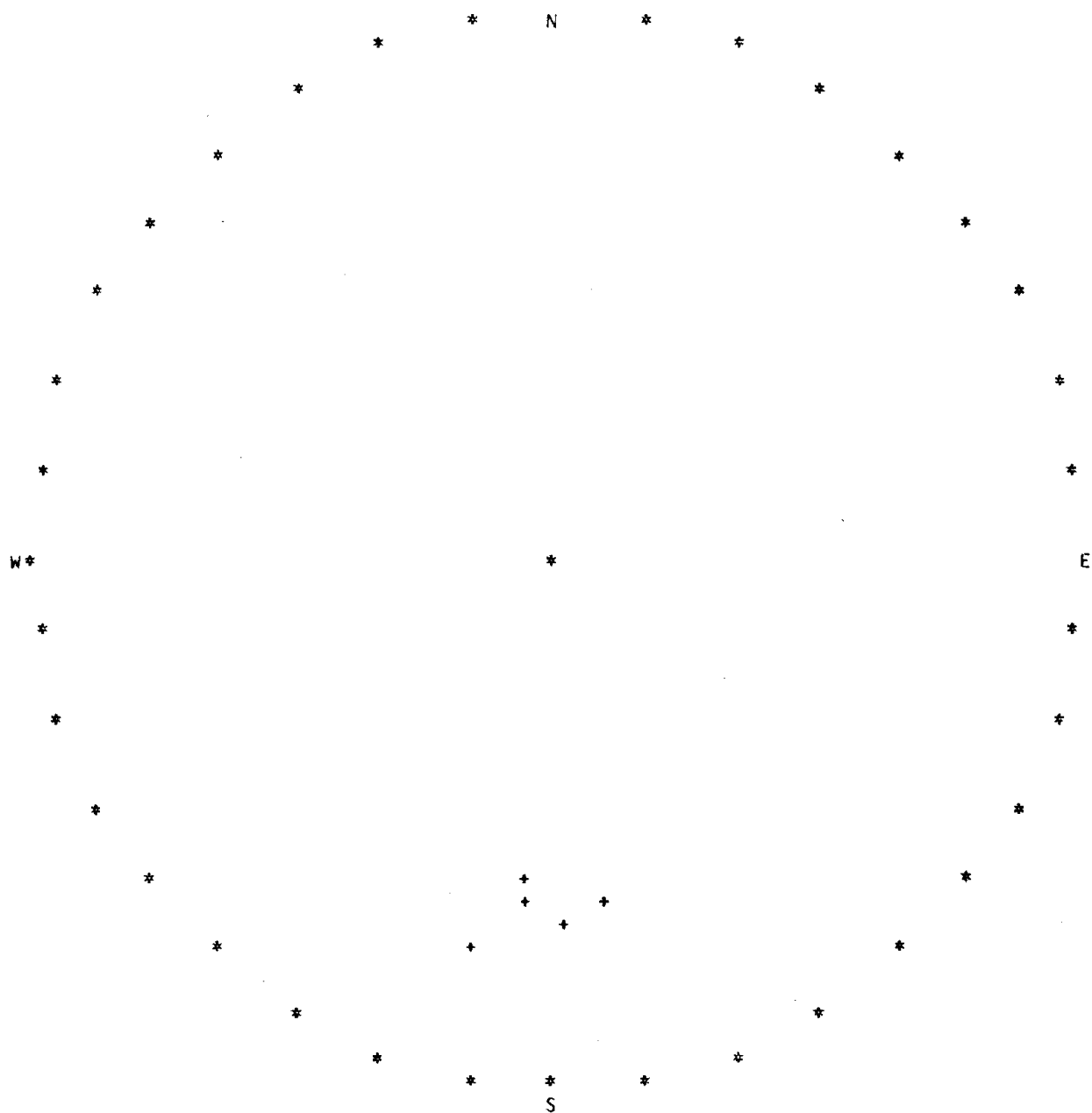
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

4.95047 -4.19976 -.23922 2.60998

CENTER OF GRAVITY - (X,Y,Z) COORDINATES

-.8400 -.0478 .5220

UPPER HEMISPHERE



CLUSTER NO. 6 CONTAINS 5 POINTS.
FOR THIS ANALYSIS, RCIS = 13.50

CLUSTER NUMBER 7

NUM	AZIMUTH	INCLINATION
1	6.00	36.00
2	335.00	37.00
3	86.00	28.00
4	94.00	29.00
5	187.00	28.00
6	341.00	30.00
7	23.00	21.00
8	26.00	20.00
9	113.00	24.00
10	257.00	22.00
11	297.00	21.00
12	356.00	21.00
13	131.00	19.00
14	201.00	17.00
15	324.00	19.00
16	14.00	14.00
17	19.00	15.00
18	42.00	9.00
19	163.00	15.00
20	230.00	10.00
21	248.00	15.00
22	302.00	8.00
23	336.00	5.00
24	168.00	4.00
25	168.00	3.00
26	261.00	3.00

MEAN

AZIMUTH 6.13 DEG

INCLINATION 4.70 DEG

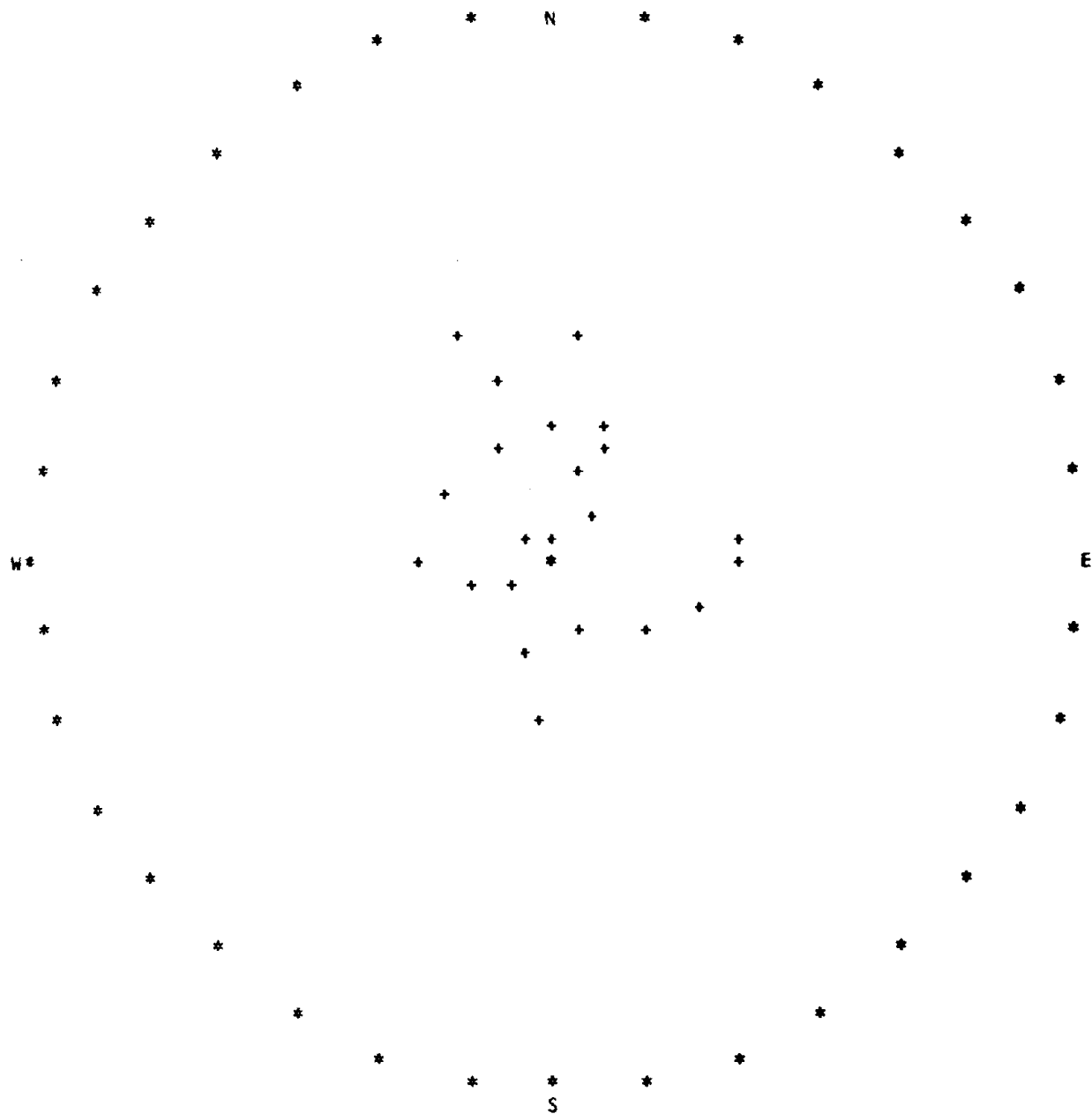
RESULTANT AND ITS COMPONENTS - R, SX, SY, SZ.

24.44680 1.99222 .21404 24.36455

CENTER OF GRAVITY - (X, Y, Z) COORDINATES

.0766 .0082 .9371

UPPER HEMISPHERE



CLUSTER NO. 7 CONTAINS 26 POINTS.
FOR THIS ANALYSIS, RDIS = 13.50

OBJECTIVE FUNCTION = 44.489

TIME REQUIRED TO ANALYZE 144 DATA POINTS 6.729 SECONDS

SUMMARY OF RESULTS

RDIS	ISPHER	LANS	PCTSURF	RANDOMNESS TEST	NO OF CLUSTERS	OBJECTIVE FUNCTION	TIME(SECONDS) REQUIRED
12.5	0	0	2.37	7	6	3.730E+01	8.584
13.5	0	0	2.76	7	7	4.449E+01	6.729

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